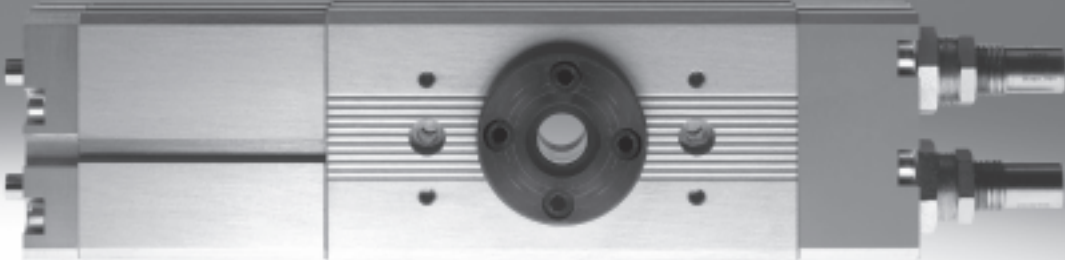


Semi-rotary drives DRQD/DRQD-B, twin pistons



Semi-rotary drives DRQD/DRQD-B, twin pistons

Key features



General

- Rack and pinion principle
- High accuracy
- Extremely good rigidity
- Backlash-free and dynamic
- Piston \varnothing 6 ... 50 mm
- Torque 0.16 ... 50 Nm
- Swivel angle 0 ... 360°
- End-position adjustment -60 ... +6°
- Defined interfaces
- Choice of mounting options
- Supply port at one end
- Ideal for use in handling applications

Wide choice of variants

Spigot shaft



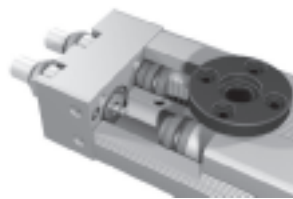
- Piston \varnothing 6 ... 50 mm

Flanged shaft



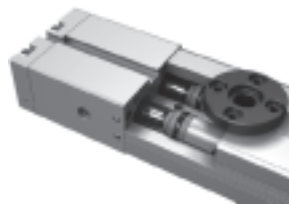
- Piston \varnothing 6 ... 50 mm

Adjustable end-position cushioning



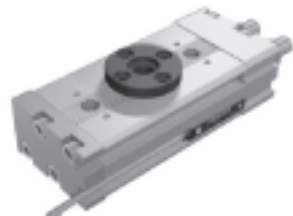
- Piston \varnothing 16 ... 50 mm
- Pneumatic
- With hydraulic shock absorbers

Intermediate position



- Piston \varnothing 16 ... 50 mm
- Allows positioning of the drive shaft in a mid-position

Position sensing



- Piston \varnothing 6 ... 50 mm
- For piston \varnothing 6 ... 12 mm: proximity sensor SME/SMT-10
- For piston \varnothing 16 ... 50 mm: proximity sensor SME/SMT-8

Adapter kits for grippers and drive combinations



- Piston \varnothing 6 ... 50 mm

Energy through-feed



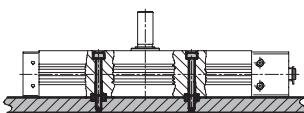
- Piston \varnothing 6 ... 50 mm
- Simple and space-saving installation of tubing through the hollow flanged shaft
- DRQD-...-SD...
1 ... 4 DUO tubes



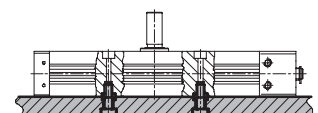
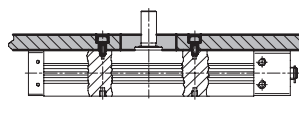
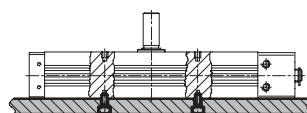
- Piston \varnothing 16 ... 50 mm
- Simple and space-saving installation of tubing and cables through the hollow flanged shaft
- DRQD-...-E...
1 ... 2 DUO tubes and 2 ... 4 electrical cables

Mounting options

using through holes



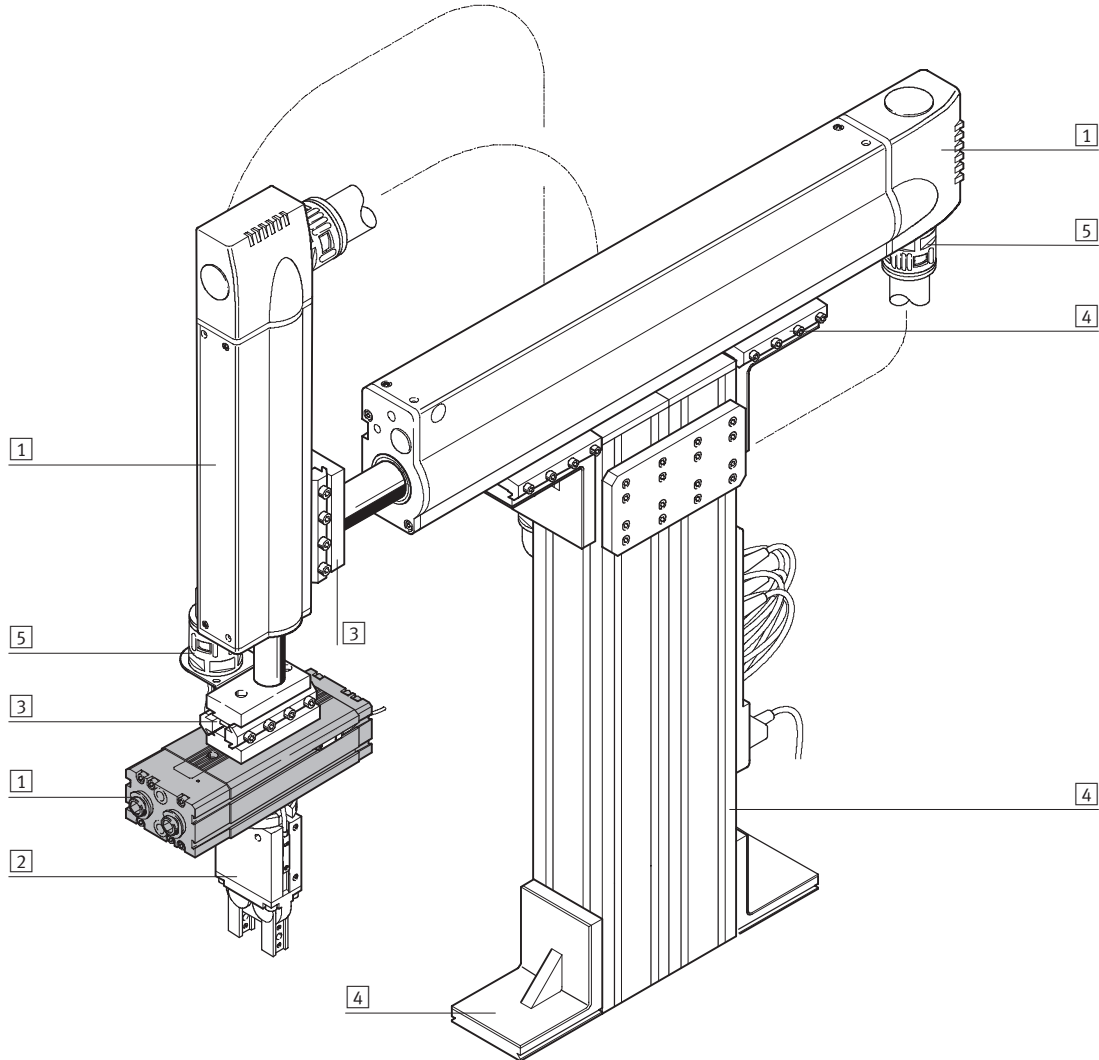
via thread in housing profile



Semi-rotary drives DRQD/DRQD-B, twin pistons

System example

System product for handling and assembly technology

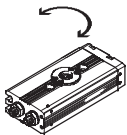
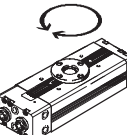


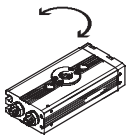
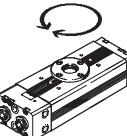
System elements and accessories		
	Brief description	→ Page/Internet
1	Drive units	Wide range of combination options within handling and assembly technology drive
2	Grippers	Wide range of combination options within handling and assembly technology gripper
3	Adapters	For drive/drive and drive/gripper combinations adapter kit
4	Basic mounting components	Profiles and profile connectors as well as profile/drive connectors basic component
5	Installation components	For achieving a clear-cut, safe layout for electrical cables and tubing installation component
-	Axes	Wide range of combination options within handling and assembly technology axes
-	Motors	Servo and stepper motors, with or without gearing motor

Semi-rotary drives DRQD/DRQD-B, twin pistons

Product range overview

FESTO

Function	Version	Type	Piston \varnothing [mm]	Swivel angle [°]	Adjustable end-position range [°]	Position sensing	End-position adjustment with flexible buffers in the end positions J...
						A	
Double- acting	Basic version						
		DRQD	6, 8, 12	90	-20 ... +6	■	■
				180	-60 ... +6		
		DRQD-B	16, 20, 25, 32	90	-20 ... +6	■	-
				180			
				360			
0 ... 340							
	DRQD	40, 50	90	-20 ... +6	■	-	
			180				
			360				
			0 ... 340				

Function	Version	Type	Piston \varnothing [mm]	Output shaft		
				Spigot shaft ZW	Flanged shaft FW	Integrated adapter for direct mounting of grippers A...
Double- acting	Basic version					
		DRQD	6, 8, 12	■	■	■
		DRQD-B	16, 20, 25, 32	■	■	-
	DRQD	40, 50	■	■	-	

Semi-rotary drives DRQD/DRQD-B, twin pistons

Product range overview

FESTO

Type	Piston \varnothing [mm]	Type of cushioning		Pneumatic connection	
		Adjustable, pneumatic PPV]	Adjustable, hydraulic shock absorbers YSR]	left AL	right AR
Basic version					
DRQD	6, 8, 12	-	-	-	■
DRQD-B	16, 20, 25, 32	■	■	■	■
DRQD	40, 50	■	■	■	■

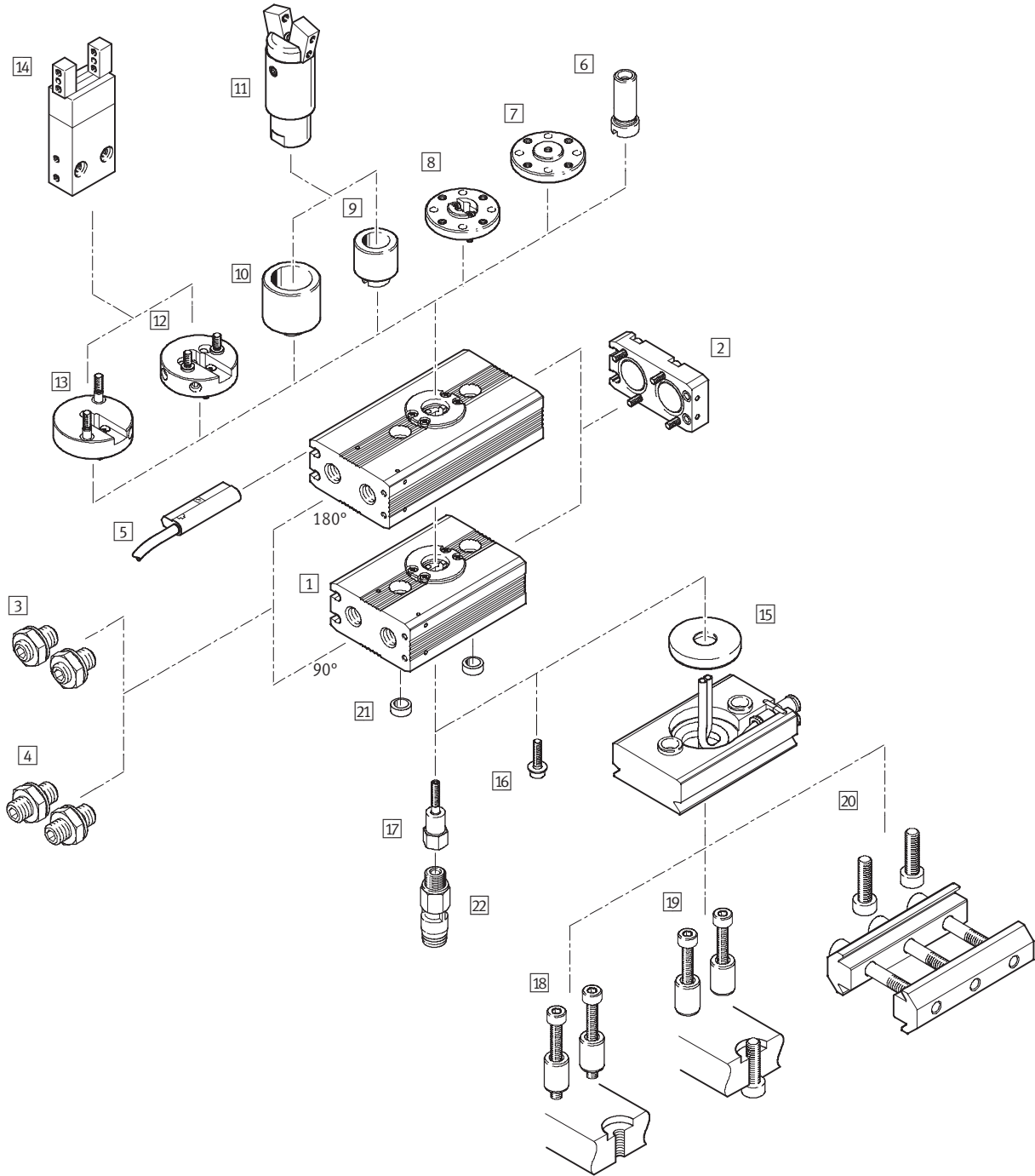
Type	Piston \varnothing [mm]	Intermediate position Z1	Energy through-feed SD..., E...	Adapter kits for grippers	→ Page/Internet
Basic version					
DRQD	6, 8, 12	-	■	■	6
DRQD-B	16, 20, 25, 32	■	■	■	22
DRQD	40, 50	■	■	■	22

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Peripherals overview

FESTO

Piston \varnothing 6 ... 12



Semi-rotary drives DRQD-6 ... 12, twin-pistons

Peripherals overview

FESTO

Variants, mounting attachments and accessories						
	Brief description	Piston Ø			→ Page/Internet	
		6	8	12		
1	Centre section	Centre section for 90° or 180° swivel angle	■	■	■	9
2	Connector cap	With integrated compressed air directional function	■	■	■	
3	End-position adjustment J20	Flexible end position cushioning with adjustable end positions (-20 ... +6°)	■	■	■	
4	End-position adjustment J60	Flexible end position cushioning with adjustable end positions (-60 ... +6°)	■	■	■	
5	Position sensing A	Contactless via proximity sensors SME-/SMT-10	■	■	■	61
6	Spigot shaft ZW ¹⁾	Hollow with woodruff key	■	■	■	9
7	Flanged shaft FW ¹⁾	Hollow	■	■	■	
8	Flanged shaft FW-SD32	Hollow, for energy through-feed	-	■	■	
9	Adapters A08 ²⁾	For grippers HGWM-08-...-G8 and HGPM-08-...-G8	■	■	■	
10	Adapters A12 ²⁾	For grippers HGWM-12-...-G8 and HGPM-12-...-G8	■	■	■	gripper
11	Grippers HGPM/HGWM	HGPM-...-G8 and HGWM-...-G8	■	■	■	
12	Adapters AS1	For grippers HGP-06-A, HGR-10-A and HGW-10-A	-	■	■	
13	Adapters AS2	For grippers HGD-16-A	-	■	■	
14	Grippers HGP/HGD/HGR/HGW	HGP-06-A, HGD-16-A, HGR-10-A, HGW-10-A	-	■	■	gripper
15	Energy through-feed SD32	2 tubes with O.D. 3 mm	-	■	■	
16	Socket head screw ZS	Mounting of ZW and FW	■	■	■	9
17	Hollow bolt HS	Mounting of ZW, FW, A08, A12 and air supply for attachments	■	■	■	
18	Type of mounting B1	For connection of DRQD/FW-SD32: Locking screws in centring sleeves	■	■	■	
19	Type of mounting B2	For connection of DRQD/FW-SD32: Through screws in attachment	■	■	■	
20	Type of mounting B3	For connection of DRQD/FW-SD32: Clamping via profile, grid 40 mm	■	■	■	14
21	Centring sleeve ZBH	For centring (2 pieces included in scope of delivery for DRQD)	■	■	■	
22	Rotary push-in fitting ³⁾ QS	Quick Star push-in fittings, rotatable with ball bearing	■	■	■	

1) The socket head screw ZS is included in the scope of delivery. The hollow bolt HS must be ordered separately

2) Only in conjunction with hollow bolt HS. The hollow bolt HS must be ordered separately

3) For energy through-feed in combination with HS

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Type codes

DRQD – 6 – 180 – J60 – A – A12 – – HS – B2 – B

Type

Double-acting	
DRQD	Semi-rotary drive

Piston Ø [mm]

Swivel angle [°]

End-position adjustment [°]

J20	-20 ... +6
J60	-60 ... +6

Position sensing

A	For proximity sensing
---	-----------------------

Output shaft/adaptor

ZW	Spigot shaft
FW	Flanged shaft
A08	Adapter for micro, angle and parallel grippers
A12	
AS1	Adapter for parallel, three-point, angle and radial grippers
AS2	

Energy through-feed

SD32	2 tubes with O.D. 3 mm
------	------------------------

Type of screw

ZS	Socket head screw
HS	Hollow bolt

Type of mounting

B1	Locking screws in centring sleeves
B2	Through screws in attachment
B3	Clamping via profile, 40 mm

User's manual

	German
E	English
F	French
S	Spanish
I	Italian
V	Swedish
B	Express waiver – no user manual to be included (already available)

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

Function

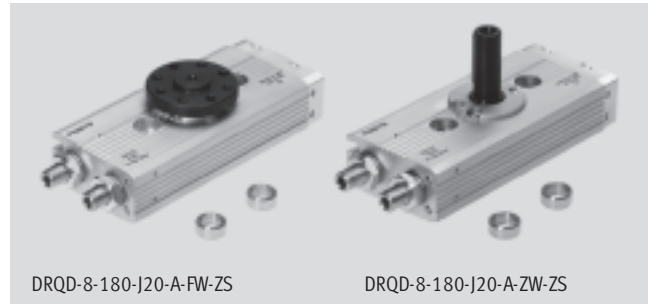


- - Diameter
6 ... 12 mm
- - Force
0.16 ... 0.76 Nm

- - www.festo.com

Variants

- 90° and 180° swivel angle
- Spigot or flanged shaft
- Adapters for grippers
- End-position adjustment
- Position sensing
- Energy through-feed
- Different types of mounting



DRQD-8-180-J20-A-FW-ZS

DRQD-8-180-J20-A-ZW-ZS

General technical data		6	8	12
Piston Ø		6	8	12
Pneumatic connection		M3		
	HS	M5		
	SD32		QS...-3 for tube O.D. 3 mm	
Constructional design	Semi-rotary drive with twin pistons based on the rack and pinion principle			
Cushioning	Flexible buffer at both ends			
Position sensing	For proximity sensing			
Type of mounting	Via through-hole			
	Via female thread			
Assembly position	Any			

Operating and environmental conditions		6	8	12
Piston Ø		6	8	12
Operating medium		Filtered compressed air, lubricated or unlubricated		
Operating pressure [bar]		1 ... 8		
	SD32		1.5 ... 8	-
Adjustable end-position range per end position [°]	J20	-20 ... +6		
	J60	-60 ... +6		
Max. permissible swivelling frequency at 6 bar (for completed cycle of motion) [Hz]	90°	5	4	3
	180°	3.5	2.5	2
	SD32		A reduction of max. 5% of the values indicated above	
Repetition accuracy [°]		< 0.2		
Ambient temperature ¹⁾ [°C]		-10 ... +60		
Corrosion resistance class CRC ²⁾		1		

1) Note operating range of proximity sensors

2) Corrosion resistance class 1 according to Festo standard 940 070

Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Semi-rotary drives DRQD-6 ... 12, twin-pistons

FESTO

Technical data

Forces and torques				
Piston Ø		6	8	12
Theoretical torque [Nm] at 6 bar		0.16	0.33	0.76
	SD32	–	0.28	0.72
		Note: If torque acts against the direction of rotation in the end position, a drive with a rating of twice the maximum theoretical torque should be selected.		
Max. permissible radial and axial forces		Diagrams → 13		
Max. permissible mass moment of inertia [kgm ²]		0.075 x 10 ⁻⁴	0.25 x 10 ⁻⁴	0.7 x 10 ⁻⁴
		The data applies to the variants ZW, FW, A... without grippers, unthrottled.		

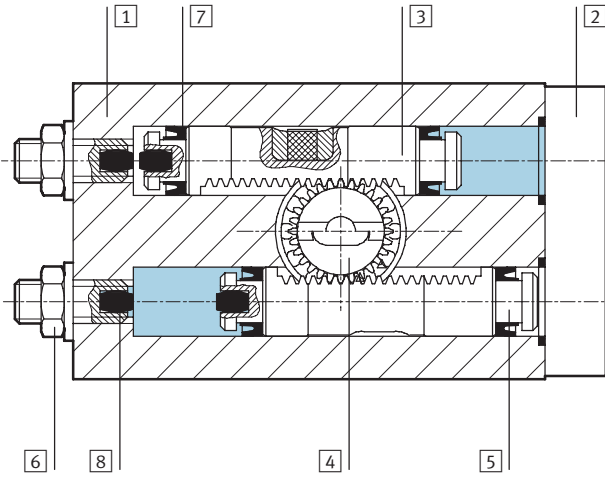
Weights [g]					
Piston Ø		6	8	12	
Centre section	90°	J20	66	90	145
		J60	67	92	148
	180°	J20	82	111	177
		J60	83	113	180
Output shaft	ZW	2	4		
	FW	4	7		
Adapters	A08	6	11		
	A12	6	11		
	AS1	–	13		
	AS2	–	15		
Screws	ZS	1			
	HS	4		5	
Flanged shaft with energy through-feed	SD32	–	71		
Mounting in combination with SD32	B1	–	17		
	B2	–	17	18	
	B3	–	81		

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

Materials

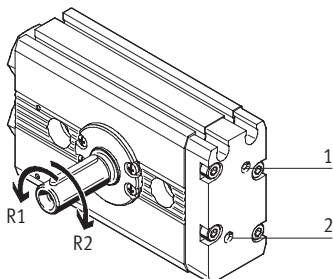
Sectional view



Piston Ø	6	8	12
1 Cylinder barrel (centre section)	Anodised aluminium		
2 Connector cap	Anodised aluminium		
3 Gear rack	Anodised aluminium		
4 Pinion	Stainless steel; milled teeth		
5 Piston	Anodised aluminium		
6 Threaded pin, hex nuts	Galvanised steel		
7 Piston seal	Nitrile rubber	Polyurethane	
8 Buffer for end-position cushioning	Nitrile rubber		
- DUO spiral tubing	Polyurethane		
- Woodruff key	Steel		
- Hollow bolt, centring sleeves	Stainless steel		
- Static seals	Steel, nitrile rubber		
- Material note	Copper, PTFE and silicone-free		

Direction of rotation of the drive shaft

Pneumatic actuation of ports 1 or 2 produces a rotational movement in direction R1 or R2 respectively.



Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

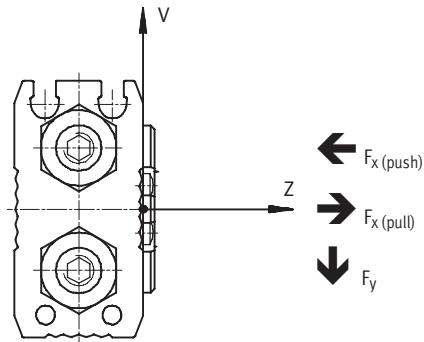


Max. permissible radial and axial forces on the drive shaft

Combined load

A semi-rotary drive DRQD-8-... is to be statically loaded with a radial force $F_y = 60\text{ N}$, which is at a distance of $Z = 5\text{ mm}$ from the housing, and an

axial force $F_{x, push} = 30\text{ N}$, which is at a distance of $V = 12\text{ mm}$ from the shaft (→ diagram of flanged shaft on right).



Question:

Is it permissible to statically load a semi-rotary drive DRQD-8-... with these combined forces?

Answer:

Graph 1 (→ 13) indicates that the maximum permissible radial force is $F_{y, max. (stat.)} (5) = 193\text{ N}$ for a distance

$Z = 5\text{ mm}$. Graph 3 (→ 13) indicates that the maximum axial force is

$F_{x, push max. (stat.)} (12) = 169\text{ N}$ for a distance $V = 12\text{ mm}$.

The following equation applies to combined loads:

$$\frac{F_y(z)}{F_{y, max. (z)}} + \frac{F_{x, push}(v)}{F_{x, push, max. (v)}} + \frac{F_{x, pull}(v)}{F_{x, pull, max. (v)}} \leq 1$$

The following values are assumed:

$F_y(5) = 60\text{ N}$
 $F_{x, push (stat.)} (12) = 30\text{ N}$
 $F_{y, max. (stat.)} (5) = 193\text{ N}$
 $F_{x, max. (stat.)} (12) = 169\text{ N}$

With values inserted:

$$\frac{60\text{ N}}{193\text{ N}} + \frac{30\text{ N}}{169\text{ N}} \leq 1$$

$$0.311 + 0.178 \leq 1$$

$$0.489 \leq 1$$

Thus the drive may be statically loaded with the forces indicated above.

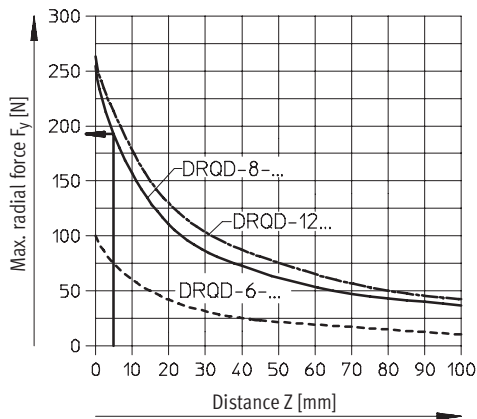
Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

Maximum static radial force

Graph 1

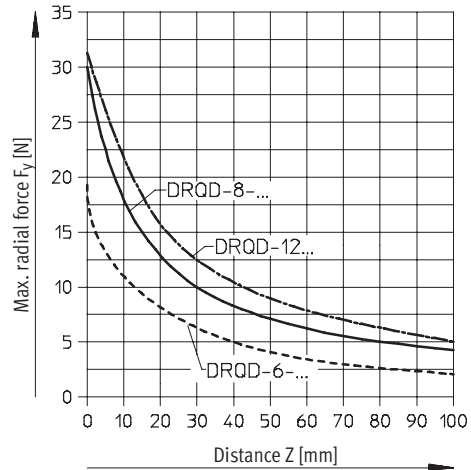
$$F_{y, \text{max. (stat.)}} = f(z)$$



Maximum dynamic radial force

Graph 2

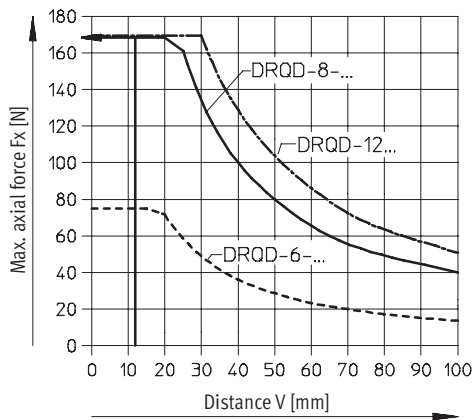
$$F_{y, \text{max. (dyn.)}} = f(z)$$



Maximum static pull and push axial forces

Graph 3

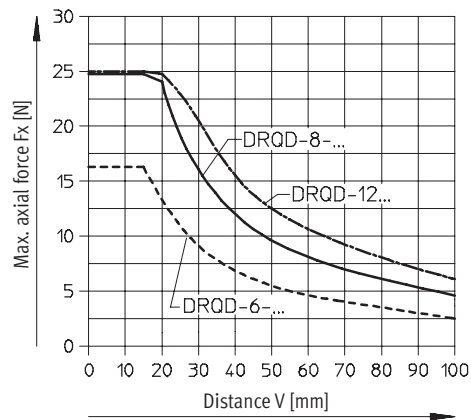
$$F_{x, \text{max. (stat.)}} = f(v)$$



Maximum dynamic pull and push axial forces

Graph 4

$$F_{x, \text{max. (dyn.)}} = f(v)$$



Semi-rotary drives DRQD-6 ... 12, twin-pistons

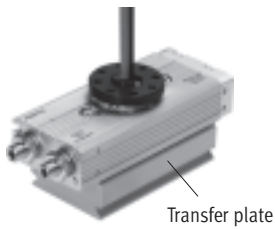
Technical data

Energy through-feed

The energy through-feed consists of DUO tubing (two lengths of tubing are fused together into a pair), whereby each tube has an O.D. of 3 mm. Compressed air is supplied via the push-in

fittings in the transfer plate. Only Quick-Star push-in fittings may be used to connect compressed air tubing to consuming devices (e.g. grippers).

DRQD-...-SD...



- For piston \varnothing 8 ... 12
- Swivel angles of up to 180° are possible
- 1 DUO tube

Technical data		8	12
Piston \varnothing		8	12
Number of spiral tubes		1 DUO tube	
Standard nominal flow rate per tube	[l/min]	min. 70	
Theoretical air consumption per tube at 6 bar	[cm ³]	5.3	
Operating pressure as a function of ambient temperature	[bar]	0 ... 10 (at -10 ... +30 °C) 0 ... 9 (at +30 ... +40 °C) 0 ... 7.8 (at +40 ... +60 °)	
Push-in fittings for connection to consuming device		QS...-3 for tube O.D. of 3 mm	

Semi-rotary drives DRQD-6 ... 12, twin-pistons

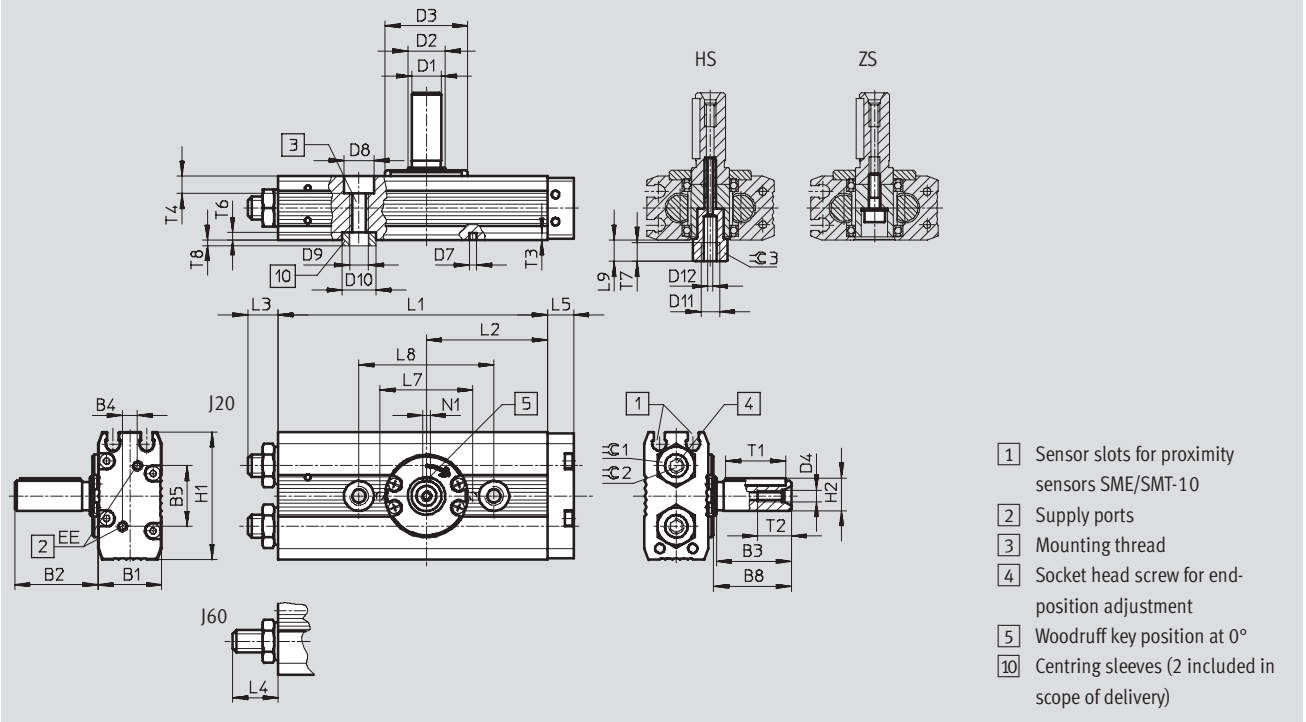
Technical data

FESTO

Dimensions

Download CAD data → www.festo.com

ZW – Spigot shaft



- 1 Sensor slots for proximity sensors SME/SMT-10
- 2 Supply ports
- 3 Mounting thread
- 4 Socket head screw for end-position adjustment
- 5 Woodruff key position at 0°
- 10 Centring sleeves (2 included in scope of delivery)

∅	Swivel angle [°]	B1	B2	B3	B4	B5	B8	D1	D2	D3 ¹⁾	D4	D7	D8	D9	D10	D11	D12	EE	H1	H2
[mm]	[°]							∅ g7	∅ g6	∅ f7		∅ H8	∅ H8		∅ H7					
6	90	15.4	18.2	16	2	13.6	16.7	6	8	20	M2.5	2	6	M4	7	M5	1.3	M3	31	6.8
	180																			
8	90	17	22.2	20	4	16.2	20.7	8	10	22	M3	-	8	M5	9	M5	1.3	M3	34	8.8
	180																			
12	90	21	22.2	20	6	18.2	20.7	8	10	22	M3	-	8	M5	9	M5	1.3	M3	41	8.8
	180																			

∅	Swivel angle [°]	L1	L2	L3	L4	L5	L7	L8	L9	N1	T1	T2	T3	T4	T6	T7	T8	≙C1	≙C2	≙C3
[mm]	[°]			max.	max.		±0.03	±0.03		P9										
6	90	46.7	20.2	7.1	11.1	7.5	20	30	6.2	2	12	7	1.8	3.4	1.6	5	1.4	8	2.5	8
	180	61.8	27.75																	
8	90	54.2	23.45	8.1	12.1	7	-	36	5.7	2	16	9	-	4.6	2	5	2	10	3	8
	180	71.8	32.25																	
12	90	59.2	25.95	9.1	13.1	8	-	36	5.7	2	16	9	-	4.6	2	5	2	13	4	8
	180	76.8	34.75																	

1) Centring possible with D3

Semi-rotary drives DRQD-6 ... 12, twin-pistons

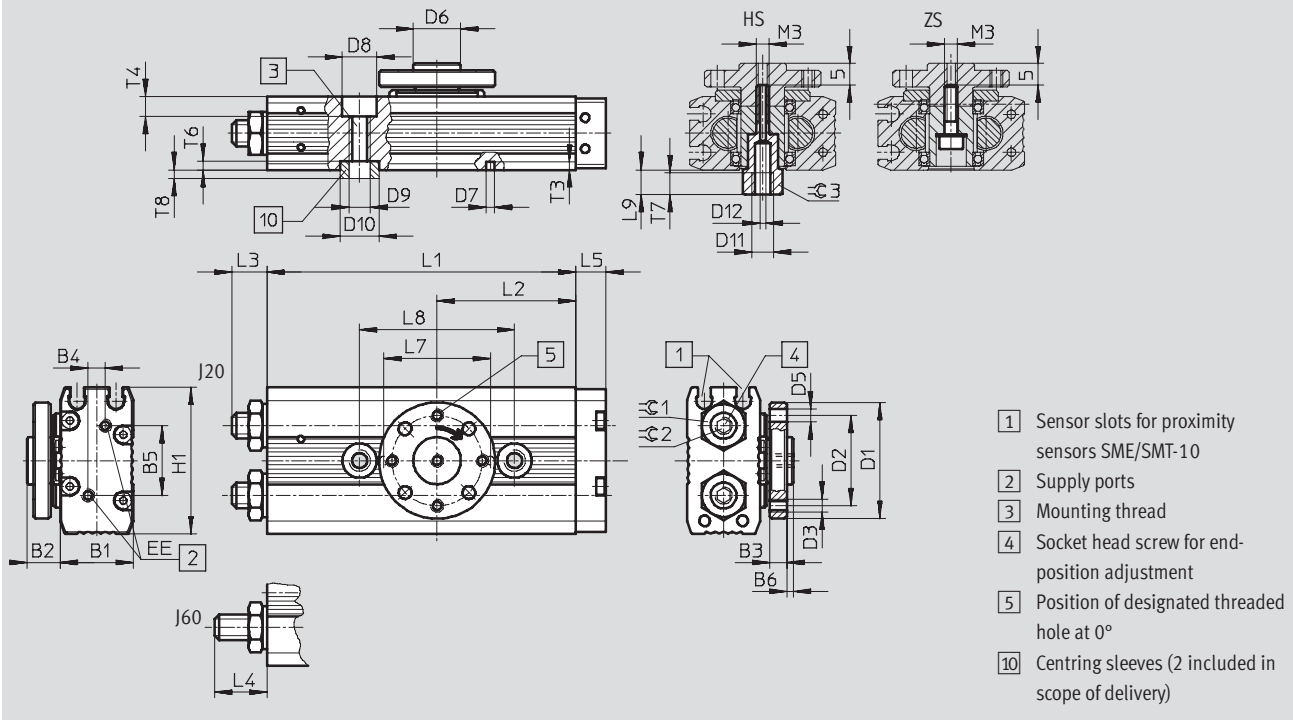
Technical data

FESTO

Dimensions

Download CAD data → www.festo.com

FW – Flanged shaft



∅	Swivel angle [°]	B1	B2	B3	B4	B5	B6	D1	D2	D3	D5	D6	D7	D8	D9	D10	D11	D12
[mm]								∅	∅		∅	∅	∅	∅		∅		∅
6	90	15.4	7.7	4	2	13.6	1.5	23	16	M3	3	8	2	6	M4	7	M5	1.3
	180																	
8	90	17	7.7	4	4	16.2	1.5	27	21	M3	3	11	-	8	M5	9	M5	1.3
	180																	
12	90	21	7.7	4	6	18.2	1.5	27	21	M3	3	11	-	8	M5	9	M5	1.3
	180																	

∅	Swivel angle [°]	EE	H1	L1	L2	L3	L4	L5	L7	L8	L9	T3	T4	T6	T7	T8	≈C1	≈C2	≈C3
[mm]						max.	max.		±0.03	±0.03									
6	90	M3	31	46.7	20.20	7.1	11.1	7.5	20	30	6.2	1.8	3.4	1.6	5	1.4	8	2.5	8
	180			61.8	27.75														
8	90	M3	34	54.2	23.45	8.1	12.1	7	-	36	5.7	-	4.6	2	5	2	10	3	8
	180			71.8	32.25														
12	90	M3	41	59.2	25.95	9.1	13.1	8	-	36	5.7	-	4.6	2	5	2	13	4	8
	180			76.8	34.75														

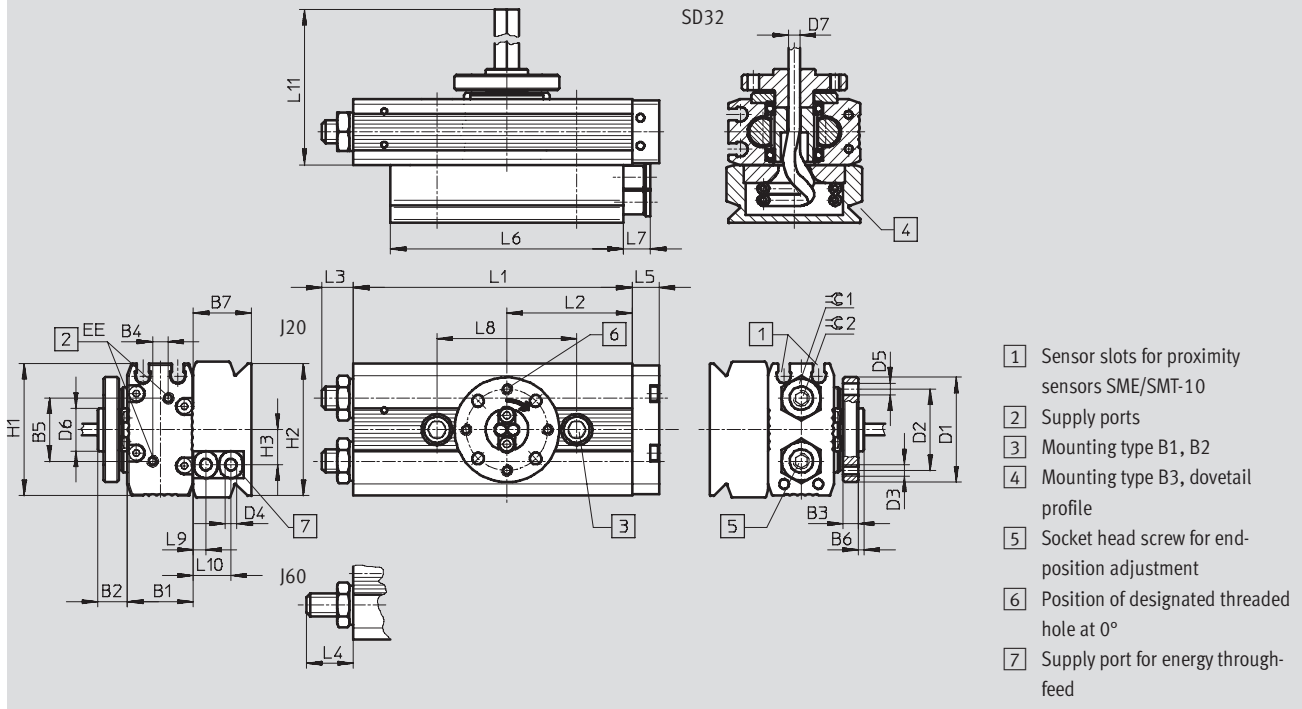
Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

Dimensions

Download CAD data → www.festo.com

FW-SD32 – Energy through-feed



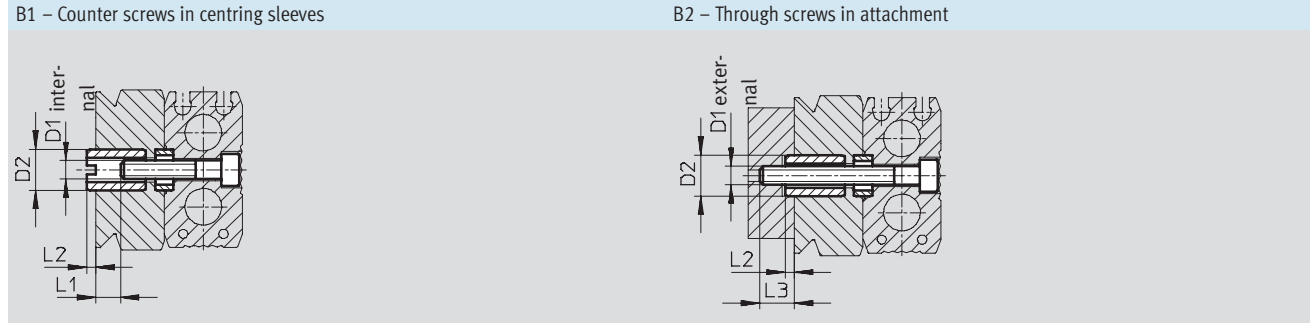
∅	Swivel angle	B1	B2	B3	B4	B5	B6	B7	D1	D2	D3	D4	D5	D6	D7	EE
[mm]	[°]								∅	∅	∅	∅	∅	∅	∅	
8	90	17	7.7	4	4	16.2	1.5	15	27	21	M3	3	3	11	3	M3
	180															M3
12	90	21	7.7	4	6	18.2	1.5	15	27	21	M3	3	3	11	3	M3
	180															M3

∅	Swivel angle	H1	H2	H3	L1	L2	L3	L4	L5	L6	L7	L8	L9	L10	L11	≡C1	≡C2
[mm]	[°]						max.	max.			±0.03						
8	90	34	35	9	54.2	23.45	8.1	12.1	7	60	7	36	3.2	9.7	292	10	3
	180				71.8	32.25											
12	90	41	35	9	59.2	25.95	9.1	13.1	8	60	7	36	3.2	9.7	292	13	4
	180				76.8	34.75											

Semi-rotary drives DRQD-6 ... 12, twin-pistons

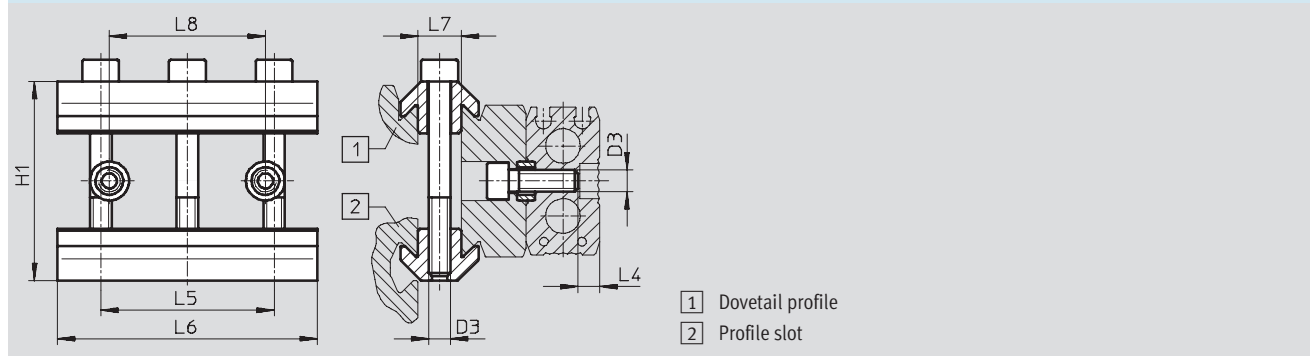
Technical data

Dimensions – Mounting type Download CAD data → www.festo.com



For Ø [mm]	Swivel angle [°]	D11	D2 Ø h7	L1	L2	L3
8	90	M4	9	4.9	2	8.2
	180					
12	90			5.9		9.2
	180					

B3 – Clamping via profile



For Ø [mm]	Swivel angle [°]	D3	H1	L4	L5	L6	L7 +0.1	L8 ±0.03
8	90	M5	46	5	40	60	10	36
	180			9				
12	90			9				
	180							

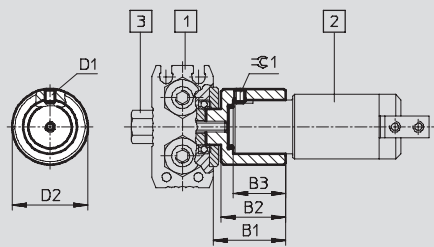
Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

Dimensions – Adapter for gripper

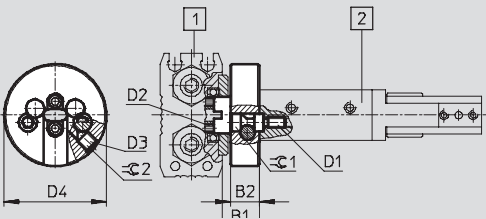
Download CAD data → www.festo.com

A08/A12

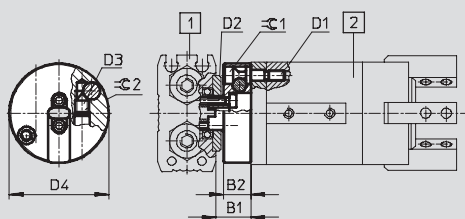


For adapter	1 Drive	2 Grippers	3 Type of screw	B1	B2	B3 ±0.03	D1	D2 ∅	≈C1
A08	DRQD-6-... DRQD-8-... DRQD-12-...	HGWM-08-...-G8 HGPM-08-...-G8	HS	15.2	13	9.6	M3	16	1.5
A12	DRQD-6-... DRQD-8-... DRQD-12-...	HGWM-12-...-G8 HGPM-12-...-G8	HS	20.2	19	14.6	M3	21	1.5

AS1



AS2



For adapter	1 Drive	2 Grippers	B1	B2	D1	D2	D3	D4 ∅	≈C1	≈C2
AS1	DRQD-8-... DRQD-12-...	HGP-06-... HGR-10-... HGW-10-...	10.2	8	M3	M2	M4	28	2.5	2
AS2	DRQD-8-... DRQD-12-...	HGD-16-...	10.2	8	M3	M2	M4	29	2.5	2

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Ordering data – Modular products

M Mandatory data →

Module No.	Function	Size	Swivel angle	End-position adjustment	Position sensing	Output shaft/ adapter
187 431	DRQD	6	90	J20	A	ZW
187 432		8	180	J60		FW
187 433		12				A08 A12 AS1 AS2
Ordering example						
187 432	DRQD	- 8	- 180	- J60	- A	- A12

Ordering table

Size	6	8	12	Condi- tions	Code	Enter code	
M Module No.	187 431	187 432	187 433				
Function	Semi-rotary drive with twin pistons				DRQD	DRQD	
Piston Ø [mm]	6	8	12		-...		
Swivel angle	90°				-90		
	180°				-180		
End-position adjustment	Adjusting range +6°/-20°				-J20		
	Adjusting range +6°/-60°				-J60		
Position sensing	For proximity sensing				-A	-A	
Output shaft/adapter	Spigot shaft			1	-ZW		
	Flanged shaft			2	-FW		
	Adapter for HGWM-08		Adapter for HGPM-08/HGWM-08		3	-A08	
	Adapter for HGWM-12		Adapter for HGPM-12/HGWM-12		3	-A12	
	-		Adapter for HGW/HGR-10-A, HGP-6-A		4	-AS1	
	-		Adapter for HGD-16-A		4	-AS2	

- | | |
|---|--|
| <p>1 ZW Not with energy through-feed SD32
Only with screw type ZS, HS</p> <p>2 FW Required for energy through-feed SD32
Only with screw type ZS, HS</p> | <p>3 A08, A12 Not with energy through-feed SD32
Only with screw type HS</p> <p>4 AS1, AS2 Required for energy through-feed SD32
Not with screw type ZS, HS</p> |
|---|--|

Transfer order code

DRQD - - - - **A** -

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Ordering data – Modular products



→ **0 Options**

Energy through-feed	Type of screw	Type of mounting	User's manual
SD32	ZS HS	B1 B2 B3	E F S I V B
- SD32	- HS	- B2	- B

Ordering table						
Size	6	8	12	Condi- tions	Code	Enter code
0 Energy through-feed	2x tubing O.D. 3 mm			5	-SD32	
Type of screw	Socket head screw				-ZS	
	Hollow bolt				-HS	
Type of mounting	Mounting type 1			6	-B1	
	Mounting type 2			6	-B2	
	Mounting type 3			6	-B3	
Alternative language user docu- mentation (standard is German)	English				-E	
	French				-F	
	Spanish				-S	
	Italian				-I	
	Swedish				-V	
	Express waiver – no user manual to be included (already available)				-B	

5 SD32 Only with mounting type B1, B2, B3

6 B1, B2, B3 Only with energy through-feed SD32

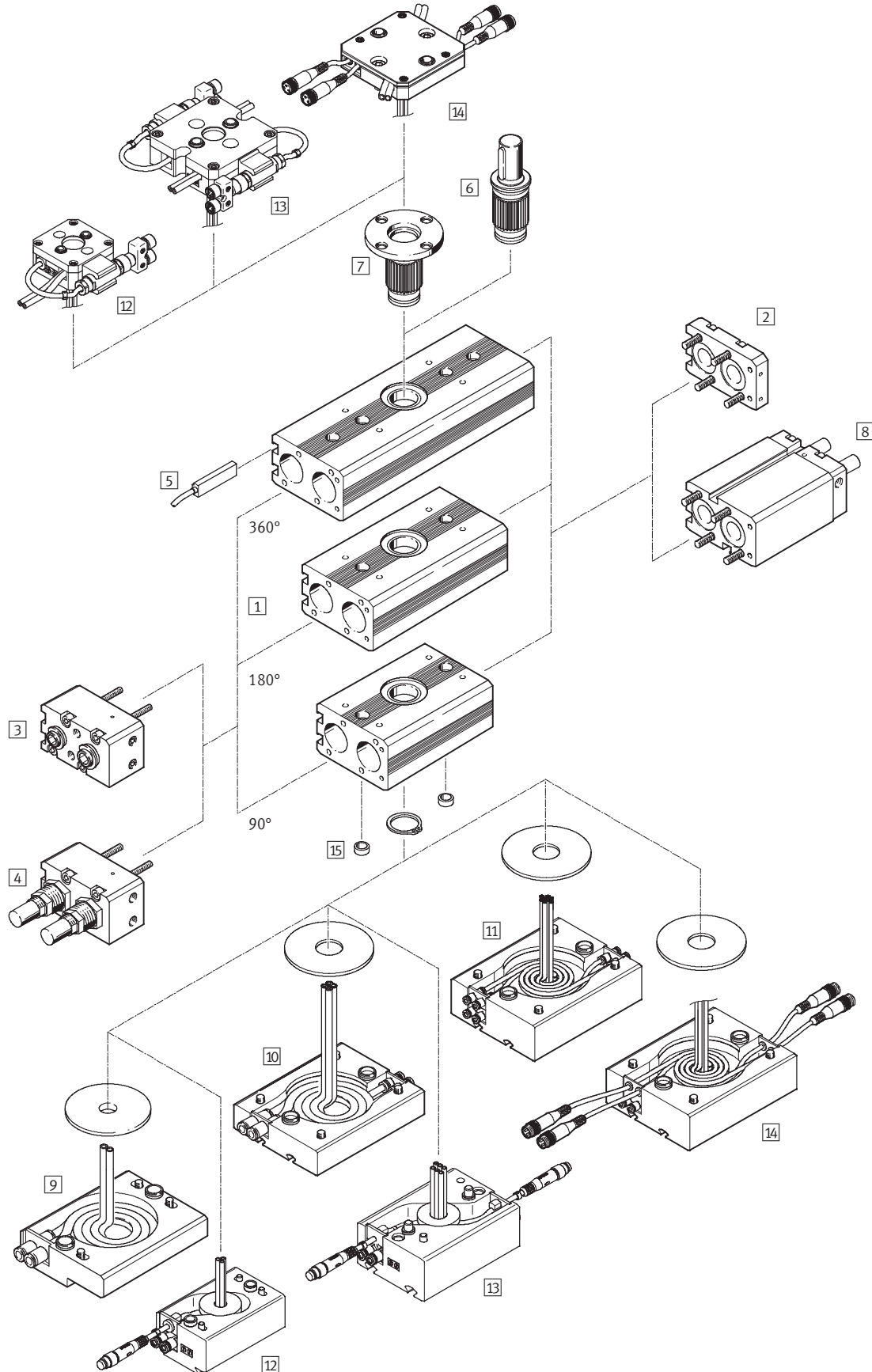
Transfer order code

- - - -

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Peripherals overview

Piston \varnothing 16 ... 50



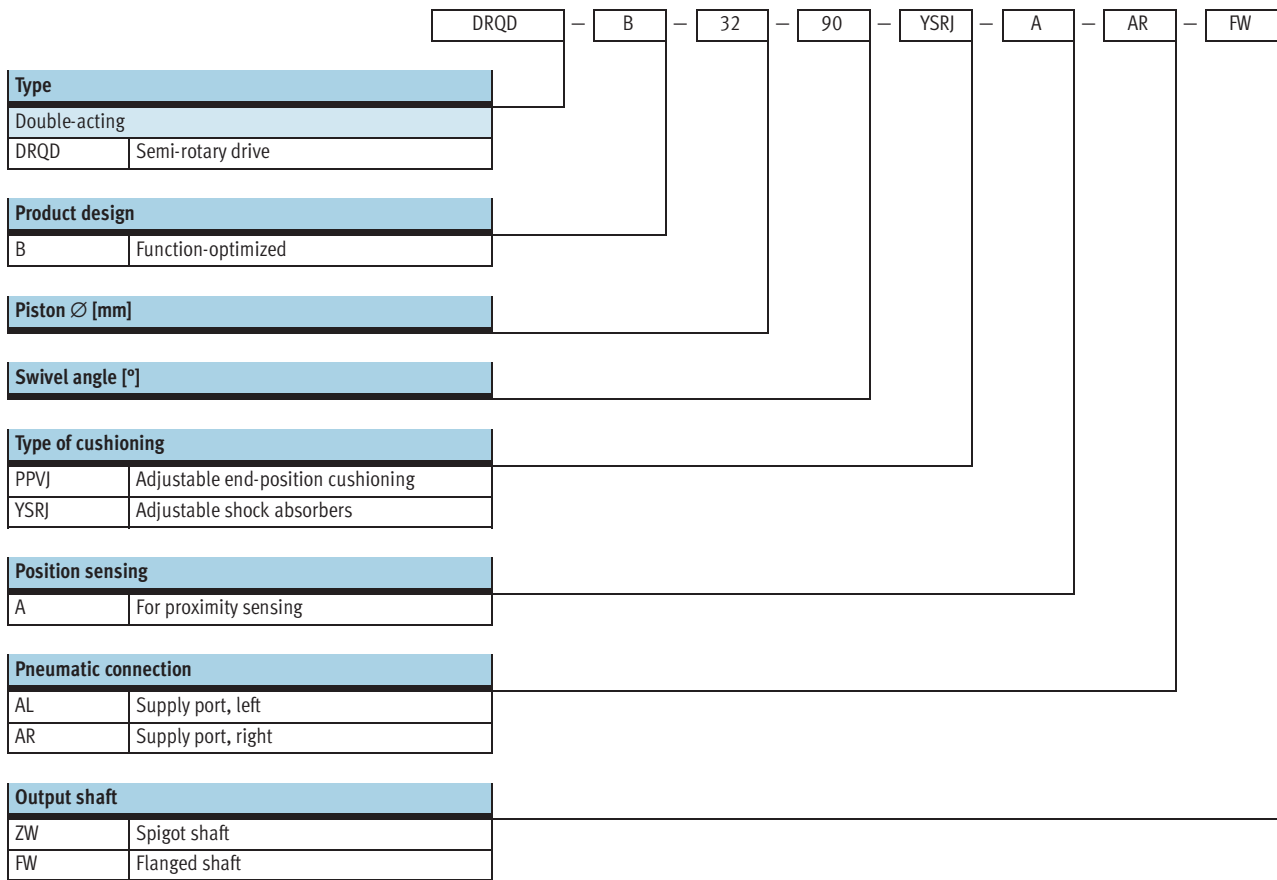
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Peripherals overview

Variants, mounting attachments and accessories									
	Brief description	Piston Ø						→ Page/Internet	
		16	20	25	32	40	50		
1	Centre section	Centre section for 90°, 180° or 360° swivel angle	■	■	■	■	■	■	56
2	End cap	With integrated compressed air directional function	■	■	■	■	■	■	
3	Connector cap PPVJ	Flexible end position cushioning with adjustable end positions (-20° ... +6°)	■	■	■	■	■	■	
4	Connector cap YSRJ	Adjustable shock absorbers with adjustable end positions (-20° ... +6°)	■	■	■	■	■	■	
5	Position sensing A	Contactless via proximity sensors SME-/SMT-8	■	■	■	■	■	■	61
6	Spigot shaft ZW	With woodruff key	■	■	■	■	■	■	56
7	Flanged shaft FW	Hollow, for energy through-feed	■	■	■	■	■	■	
8	Intermediate position Z1	Mid-position at centre of nominal angles of rotation of 90° and 180° (±10°)	■	■	■	■	■	■	33
9	Energy through-feed SD32, SD42	2 tubes with O.D. 3 or 4 mm	■	■	■	■	-	-	34
	Energy through-feed SD62	2 tubes with O.D. 6 mm	-	-	-	-	■	■	
10	Energy through-feed SD64	4 tubes with O.D. 6 mm	-	-	-	-	■	■	
11	Energy through-feed SD48	8 tubes with O.D. 4 mm	-	-	-	-	■	■	
12	Energy through-feed E422	2 tubes with O.D. 4 mm and 1 4-pin cable to 2 3-pin cables	■	■	-	-	-	-	
13	Energy through-feed E444	4 tubes with O.D. 4 mm and 2 4-pin cables to 4 3-pin cables	-	-	■	■	-	-	
14	Energy through-feed E644	4 tubes with O.D. 6 mm and 4 3-pin cables	-	-	-	-	■	■	
15	Centring sleeve ZBH	For centring (2 pieces included in scope of delivery for DRQD)	■	■	■	■	■	■	60

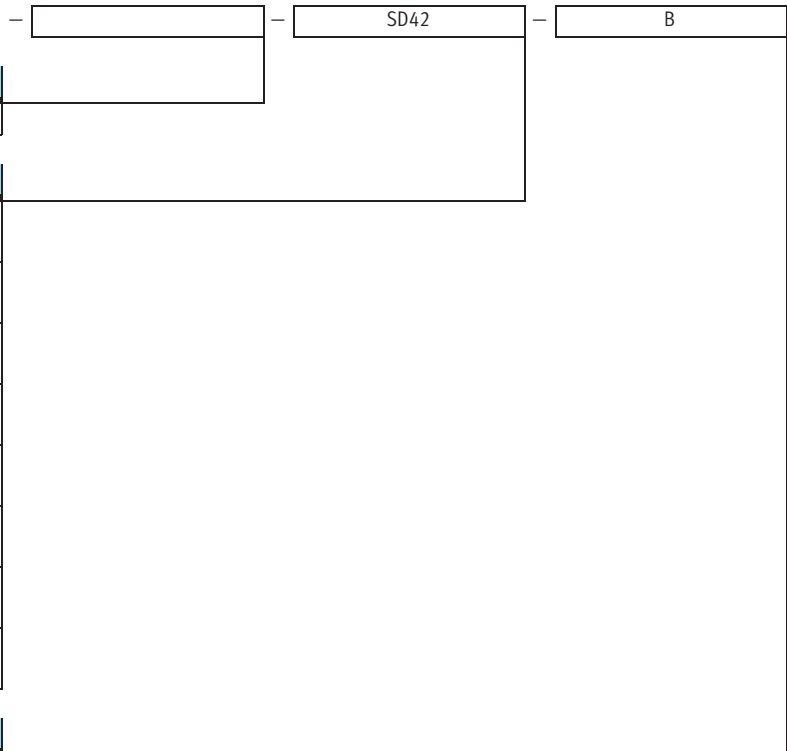
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Type codes



Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Type codes



Intermediate position	
Z1	1 intermediate position (mid-position)

Energy through-feed	
SD32	2 tubes with O.D. 3 mm
SD42	2 tubes with O.D. 4 mm
SD48	8 tubes with O.D. 4 mm
SD62	2 tubes with O.D. 6 mm
SD64	4 tubes with O.D. 6 mm
E422	2 tubes with O.D. 4 mm and 1 4-pin cable to 2 3-pin cables
E444	4 tubes with O.D. 4 mm and 2 4-pin cables to 4 3-pin cables
E644	4 tubes with O.D. 6 mm and 4 3-pin cables

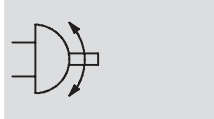
User's manual	
	German (standard)
E	English
F	French
S	Spanish
I	Italian
V	Swedish
B	Express waiver – no user manual to be included (already available)

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

FESTO

Technical data

Function



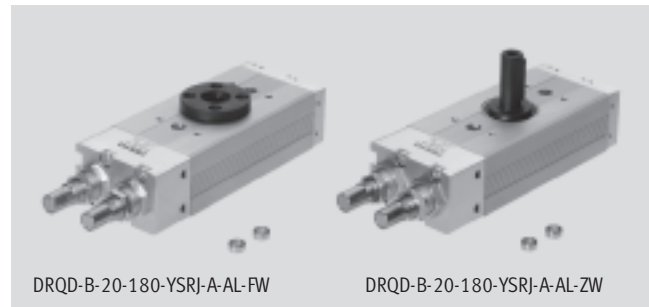
⊘ - Diameter
16 ... 50 mm

≡ - Force
1.6 ... 50 Nm

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Variants

- 90°, 180° and 360° or X swivel angle
- Spigot or flanged shaft
- Adjustable end-position cushioning or shock absorbers
- Position sensing
- Intermediate position
- Energy through-feed
- Different types of mounting



General technical data		16	20	25	32	40	50
Piston ∅		16	20	25	32	40	50
Pneumatic connection		M5			G1/8		G1/4
	SD32	QS...-3 for tubing O.D. ∅ 3 mm ¹⁾				-	-
	SD42/SD48	QS...-4 for tubing O.D. ∅ 4 mm ¹⁾				-	-
	E422	QS...-4 for tubing O.D. 4 mm		-			
	E444	-		QS...-4 for tubing O.D. 4 mm		-	
	SD62/SD64/ E644	-				QS...-6 for tubing O.D. 6 mm	
Constructional design		Semi-rotary drive with twin pistons based on the rack and pinion principle					
Cushioning	PPVJ	Adjustable, pneumatic					
	YSRJ	Adjustable, hydraulic shock absorbers					
Position sensing		For proximity sensing					
Type of mounting		Via through-hole					
		Via female thread					
Assembly position		Any					

Operating and environmental conditions		16	20	25	32	40	50	
Operating medium		Filtered compressed air, lubricated or unlubricated						
Operating pressure [bar]	PPVJ	1 ... 10						
	YSRJ	2 ... 10						
	Z1	1 ... 10						
Adjustable end-position range per end position [°]	PPVJ	-20 ... +6						
	YSRJ							
Max. permissible swiveling frequency at 6 bar (for completed cycle of motion) [Hz]	PPVJ	90°	4	3	2	1.2	1.2	1.2
		180°	3	2.2	1.3	0.8	0.9	0.9
		360°	1.5	1.2	0.8	0.5	0.5	0.5
	YSRJ	90°	2	2	1.5	1.2	1	0.9
		180°	1.8	1.8	1.5	1.2	1	0.8
		360°	1	1	0.9	0.8	0.7	0.6
SD.../E...		A reduction of max. 5% of the values indicated above						
		Note: At temperatures < 0 °C, a max. frequency of 1 Hz applies in the case of variant YSRJ.						

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Operating and environmental conditions									
Piston Ø				16	20	25	32	40	50
Minimum cycle times [s] PPVJ	90°	in conjunction with Z1	(from the end position to the intermediate position)	0.20	0.22	0.18	0.21	0.20	0.18
				0.26	0.41	0.20	0.26	0.21	0.35
	180°	YSRJ	0.20	0.22	0.17	0.20	0.47	0.35	
			0.23	0.31	0.22	0.23	1.10	0.99	
Repetition accuracy [°] (approached from both ends)				≤ 0.05					
Z1				≤ 0.15			≤ 0.25	≤ 0.20	≤ 0.30
Ambient temperature [°C]				-10 ... +60					
Corrosion resistance class CRC ¹⁾				1					

1) Corrosion resistance class 1 according to Festo standard 940 070
 Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Forces and torques										
Piston Ø				16	20	25	32	40	50	
Theoretical torque at 6 bar [Nm] PPVJ				1.6	3.1	6.1	12.5	25	50	
				YSRJ	1.6	3.1	6.1	12.5	25	50
				Z1	1.7	3.6	6.2	13.5	32.2	78.6
				Note: If torque acts against the direction of rotation in the end position, a drive with a rating of twice the maximum theoretical torque should be selected.						
Max. permissible radial and axial forces				Graphs → 31						
Max. permissible mass moment of inertia [kgm ²] PPVJ				5 x 10 ⁻⁴	10 x 10 ⁻⁴	20 x 10 ⁻⁴	40 x 10 ⁻⁴	200 x 10 ⁻⁴	500 x 10 ⁻⁴	
				YSRJ	Graphs → 29					
				PPVJ-Z1	5 x 10 ⁻⁴	10 x 10 ⁻⁴	20 x 10 ⁻⁴	40 x 10 ⁻⁴	200 x 10 ⁻⁴	500 x 10 ⁻⁴
				YSRJ-Z1	-	-	-	-	1000 x 10 ⁻⁴	2000 x 10 ⁻⁴
The data applies to the variants ZW, FW, without grippers and unthrottled.										

Weights [g]										
Piston Ø				16	20	25	32	40	50	
Connection cap AL/AR				PPVJ	116	220	358	609	1,170	2,320
				YSRJ	140	240	441	917	2,170	4,270
Centre section/output shaft	90°	ZW	379	609	1,026	1,891	3,330	6,860		
			FW	380	586	1,018	1,848	3,960	7,010	
	180°	ZW	467	753	1,267	2,325	4,340	8,850		
		FW	468	730	1,259	2,282	4,570	9,000		
	360°	ZW	643	1,039	1,741	3,199	6,350	12,890		
		FW	644	1,016	1,733	3,165	6,580	13,040		
End cap				40	53	82	140	370	610	
Intermediate position	90°	Z1	235	315	550	805	2,510	3,960		
			180°	Z1	235	315	550	805	2,510	3,960
Flanged shaft with energy through-feed	SD32	152			303			-		
		SD42	152			303			-	
	SD48	-			-			1,220		
	SD62	-			-			900		
	SD64	-			-			930		
	E422	400			-			-		
	E444	-			800			-		
	E644	-			-			2,700		

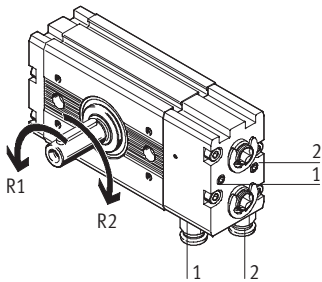
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Direction of rotation of the drive shaft

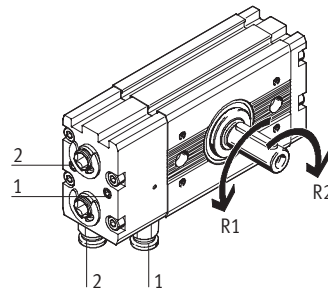
Connection cap on right (AR)

Pneumatic actuation of ports 1 or 2 produces a rotational movement in direction R1 or R2 respectively.



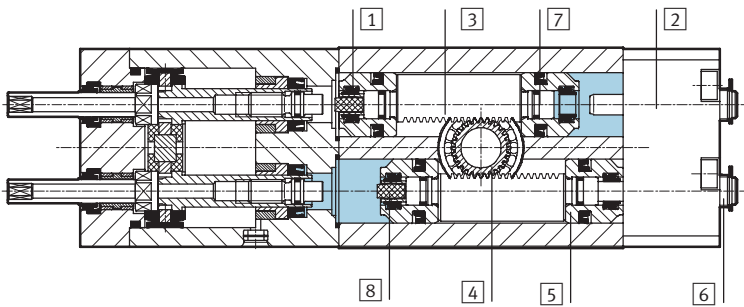
Connection cap on left (AL)

Pneumatic actuation of ports 1 or 2 produces a rotational movement in direction R1 or R2 respectively.



Materials

Sectional view



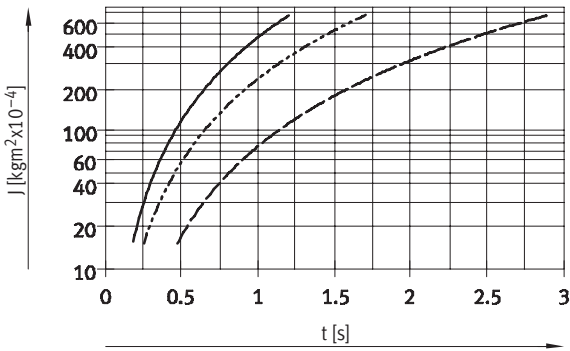
Piston Ø	16	20	25	32	40	50
Basic drive						
1	Cylinder barrel (centre section)		Anodised aluminium		Wrought aluminium alloy, anodised	
2	Connector cap		Anodised aluminium			
3	Gear rack		High-alloy stainless steel, hardened		High-alloy steel	
4	Pinion		Tempered steel			
5	Piston		Anodised aluminium			
6	Adjustable sleeve		Galvanised steel			
7	Piston seal		Polyurethane			
-	Material note		Copper, PTFE and silicone-free			
Function end cap PPVJ						
-	Cushioning seal		Nitrile rubber/polyurethane		Polyurethane	
-	Buffer sleeve, regulating screw		Anodised aluminium			
Function end cap YSRJ						
-	Buffer		Delrin			
-	Rod wiper seal		Nitrile rubber/polyurethane			
Energy through-feed SD.../E...						
-	Transfer plate/sliding disc		Anodised aluminium			
-	DUO spiral tubing		Polyurethane			
Z1 intermediate position module						
-	Piston		Stainless steel; nitrile rubber			
-	Piston rod, nut		Stainless steel			
-	Bearings		POM			
-	Rod wiper seal		Polyurethane			

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

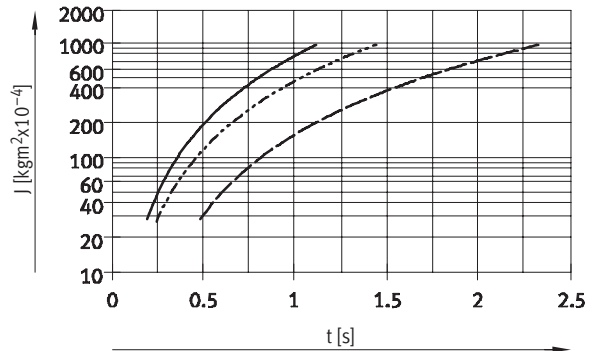
Maximum permitted mass moment of inertia J on the output shaft as a factor of swivel time t

DRQD-B-16-...-YSRJ



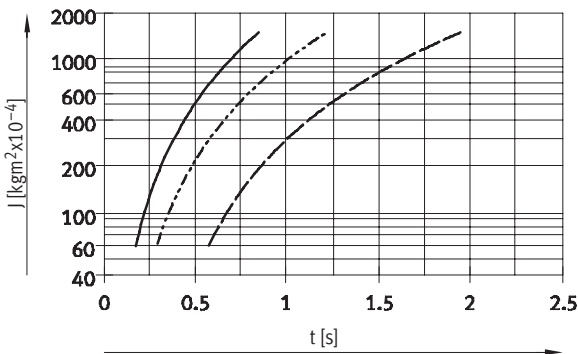
Max. permitted mass moment = 700 kgm²x10⁻⁴

DRQD-B-20-...-YSRJ



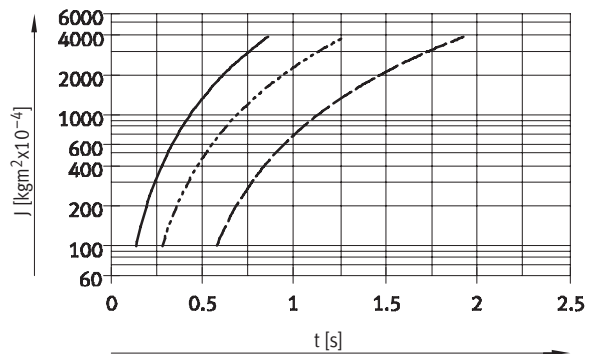
Max. permitted mass moment = 1 000 kgm²x10⁻⁴

DRQD-B-25-...-YSRJ



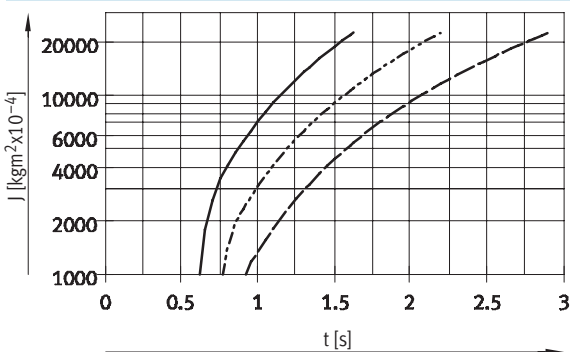
Max. permitted mass moment = 1 500 kgm²x10⁻⁴

DRQD-B-32-...-YSRJ



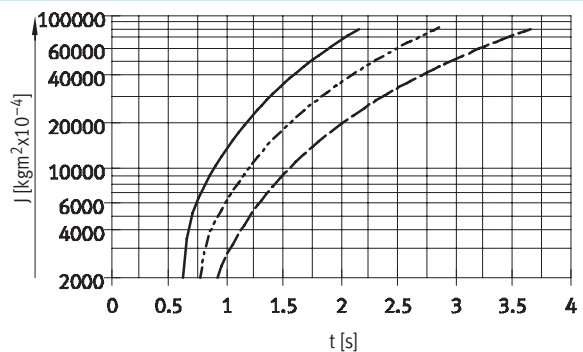
Max. permitted mass moment = 4 000 kgm²x10⁻⁴

DRQD-40-...-YSRJ



Max. permitted mass moment = 23 000 kgm²x10⁻⁴

DRQD-50-...-YSRJ



Max. permitted mass moment = 83 000 kgm²x10⁻⁴

- 90°
- - - 180°
- · - 360°

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

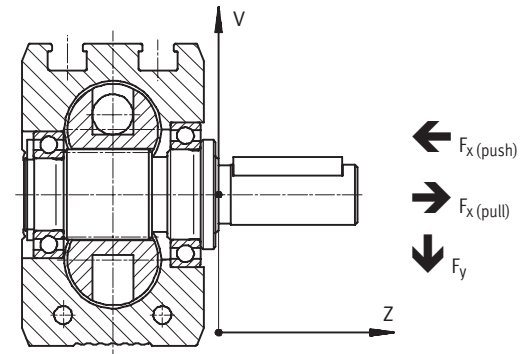
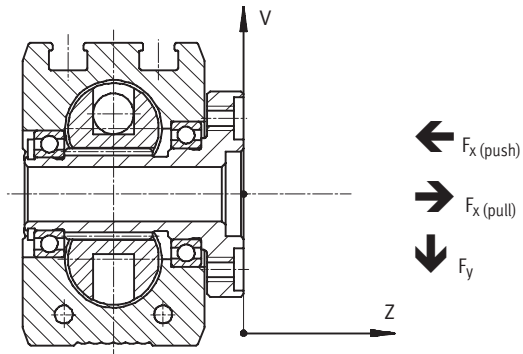


Max. permissible radial and axial forces on the drive shaft

Combined load

A DRQD-B-16-...-FW is to be statically loaded with a radial force $F_y = 300\text{ N}$, which is at a distance of $Z = 15\text{ mm}$ from the flanged shaft, and an axial

force $F_{x, \text{push}} = 100\text{ N}$, which is at a distance of $V = 25\text{ mm}$ from the shaft (→ diagram of flanged shaft on right).



Question:

Is it permissible to statically load a DRQD-B-16-...-FW with these combined forces?

Answer:

According to graph 1 (→ 31), a distance of $Z = 15\text{ mm}$ results in a maximum permissible radial force

$F_{y, \text{max. (stat.)}}(15) = 400\text{ N}$.
According to graph 3 (→ 31), a distance of $V = 25\text{ mm}$ results in a maxi-

mum permissible axial force
 $F_{x, \text{push max. (stat.)}}(25) = 550\text{ N}$.

The following equation applies to combined loads:

$$\frac{F_{y(z)}}{F_{y, \text{max. (z)}}} + \frac{F_{x, \text{push}(v)}}{F_{x, \text{push, max. (v)}}} + \frac{F_{x, \text{pull}(v)}}{F_{x, \text{pull, max. (v)}}} \leq 1$$

The following values are assumed:

$F_{y(15)} = 300\text{ N}$
 $F_{x, \text{push (stat.)}}(25) = 100\text{ N}$
 $F_{y, \text{max. (stat.)}}(15) = 400\text{ N}$
 $F_{x, \text{max. (stat.)}}(25) = 550\text{ N}$

With values inserted:

$$\frac{300\text{ N}}{400\text{ N}} + \frac{100\text{ N}}{550\text{ N}} \leq 1$$

$$0.75 + 0.182 \leq 1$$

$$0.932 \leq 1$$

Thus the drive may be statically loaded with the forces indicated above.

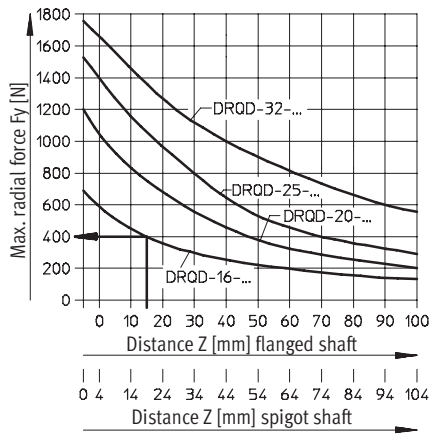
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Maximum static radial force

Graph 1

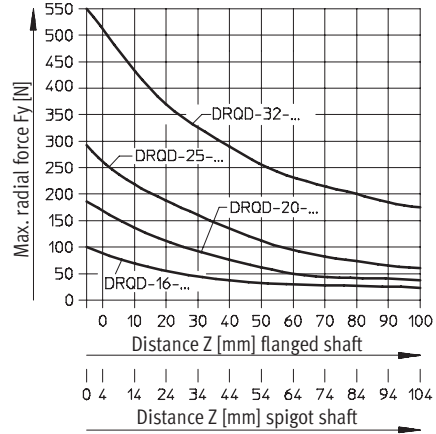
$$F_{y, \text{max. (stat.)}} = f(z)$$



Maximum dynamic radial force

Graph 2

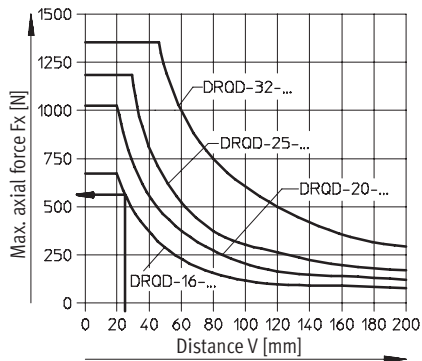
$$F_{y, \text{max. (dyn.)}} = f(z)$$



Maximum static axial pushing force

Graph 3

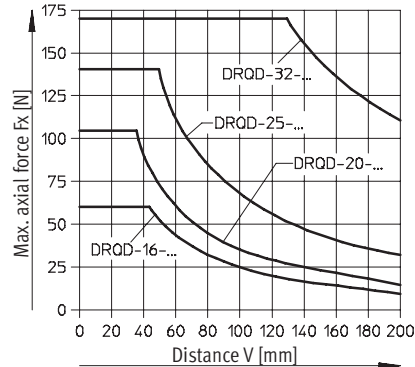
$$F_{x, \text{push max. (stat.)}} = f(v)$$



Maximum dynamic axial pushing force

Graph 4

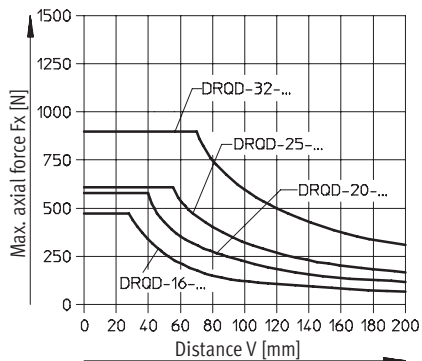
$$F_{x, \text{push max. (dyn.)}} = f(v)$$



Maximum static axial pulling force

Graph 5

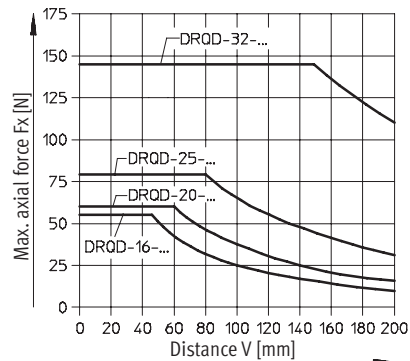
$$F_{x, \text{pull max. (stat.)}} = f(v)$$



Maximum dynamic axial pulling force

Graph 6

$$F_{x, \text{pull max. (dyn.)}} = f(v)$$



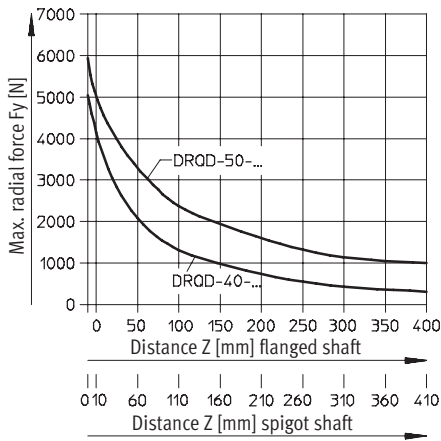
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Maximum static radial force

Graph 1

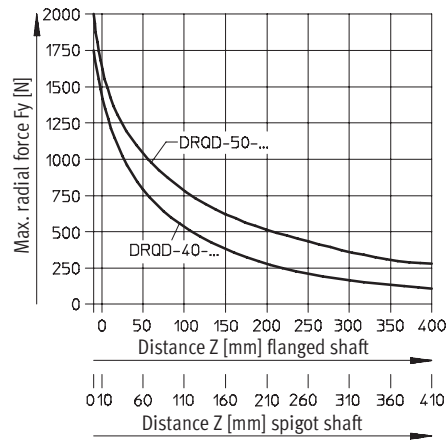
$$F_{y, \text{max. (stat.)}} = f(z)$$



Maximum dynamic radial force

Graph 2

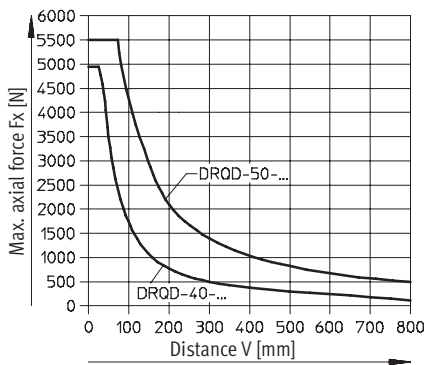
$$F_{y, \text{max. (dyn.)}} = f(z)$$



Maximum static axial pushing force

Graph 3

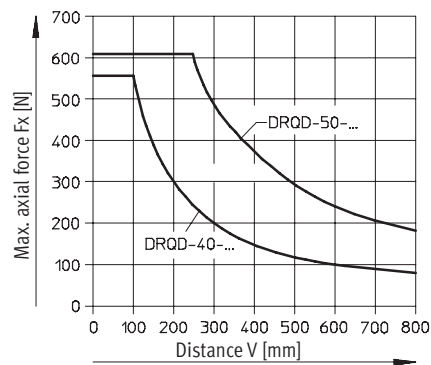
$$F_{x, \text{push max. (stat.)}} = f(v)$$



Maximum dynamic axial pushing force

Graph 4

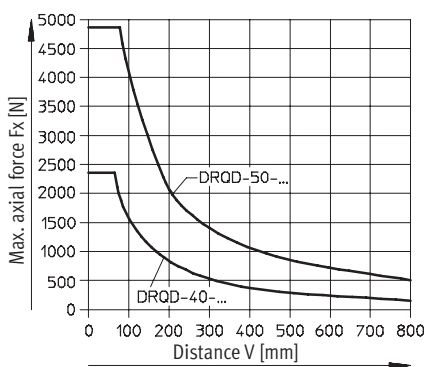
$$F_{x, \text{push max. (dyn.)}} = f(v)$$



Maximum static axial pulling force

Graph 5

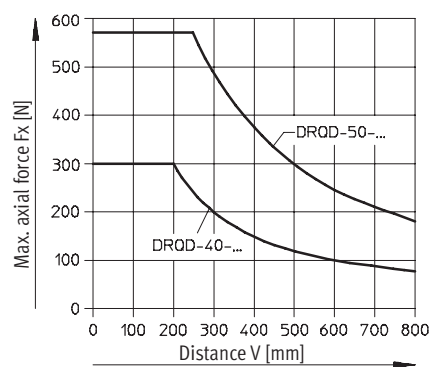
$$F_{x, \text{pull max. (stat.)}} = f(v)$$



Maximum dynamic axial pulling force

Graph 6

$$F_{x, \text{pull max. (dyn.)}} = f(v)$$



Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

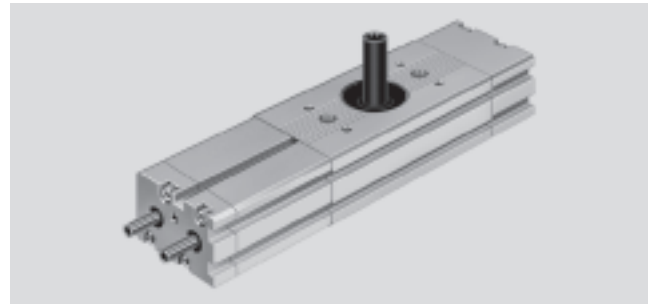
Technical data

Z1 intermediate position module

For $\varnothing 16 \dots 50$

The intermediate position module is fitted in place of the end cap, and allows for adjustable, backlash-free positioning of the drive at 50% of its

nominal rotation angle. The intermediate position module is available for nominal rotation angles of 90° and 180° .



Function

A piston incorporating two screw fastened piston rods is pressurised and shifts the semi-rotary drive gear racks until both make full contact with the

piston rods in the mid-position module. The mid-position can be accurately adjusted within a range of $\pm 10^\circ$ with the adjusting screws in the piston

rods. Thanks to the hollow shaft design of the piston rod, adjustment can be performed under pressure. The through rods in the mid-position

module are guided by means of multiple bearings in the cover and in the adapter.

Actuation

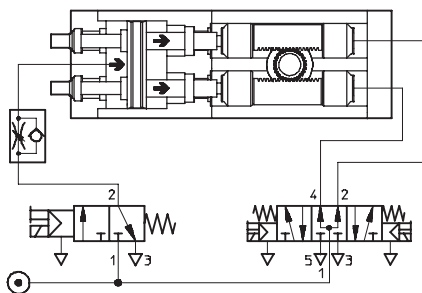
In order for the mid-position module to function, the DRQD basic actuator must be pressurised at both sides.

This can be accomplished with two different types of actuation:

Actuation type 1

- Mid-position module (supply air must be restricted) with a 3/2-way valve

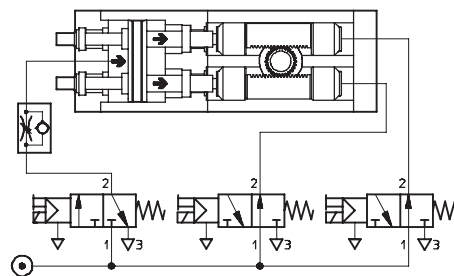
- DRQD basic drive with a 5/3-way valve, mid-position pressurised



Actuation type 2

- Mid-position module (supply air must be restricted) with a 3/2-way valve

- DRQD basic drive with two 3/2-way valves, spring return



Note

Even if the semi-rotary drives DRQD-B-16 to 32 have been equipped with shock absorbers (type YSRJ), the mid-position may not be loaded with

more than the max. permissible mass moment of inertia for the PPVJ variant! The reason for this is the cushioning: Whereas loads can be absorbed in the

end positions with the shock absorbers, the mid-position is only equipped with basic flexible cushioning. Additional information on the

permissible mass moment of inertia for the sizes 40 and 50 mm: **→ 27**

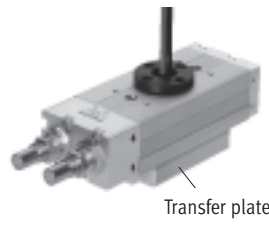
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Energy through-feed

DRQD-...-SD...	DRQD-...-E...
The energy through-feed consists of one to max. four DUO tubes (fused tubing pair), whereby each tube has an O.D. of 3 ... 6 mm. Compressed air is supplied via the push-in fittings in	The energy through-feed consists of one to max. two DUO tubes (fused tubing pair), whereby each tube has an O.D. of 4 ... 6 mm. Compressed air is supplied via the push-in fittings in the transfer plate. Only Quick-Star
the transfer plate. Only Quick-Star push-in fittings may be used to connect compressed air tubing to consuming devices (e.g. grippers).	push-in fittings may be used to connect compressed air tubing to consuming devices (e.g. grippers). In addition, up to four proximity sensors can be connected by means of this energy through-feed.

DRQD-...-SD...



- For piston \varnothing 16 ... 50
- Swivel angles of up to 360° are possible
- 1 ... 4 DUO tubes

Technical data

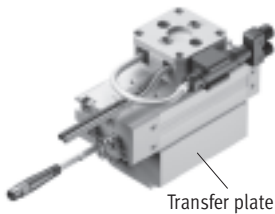
Piston \varnothing		16	20	25	32	40	50	
Number of DUO tubes	SD32	1				–		
	SD42	1				–		
	SD48	–				4		
	SD62	–				1		
	SD64	–				2		
Standard nominal flow rate (per tube) [l/min]	SD32	min. 70				–		
	SD42	min. 130				–		
	SD48	–				min. 130		
	SD62	–				min. 250		
	SD64	–				min. 250		
Theoretical air consumption per line at 6 bar [cm ³]	SD32	5.3				–		
	SD42	9.5				–		
	SD48	–				9.5		
	SD62	–				24.4		
	SD64	–				24.4		
Operating pressure as a function of ambient temperature [bar]		0 ... 10 (at –10 ... +30 °C)						
		0 ... 9 (at –30 ... +40 °C)						
		0 ... 7 (at –40 ... +60 °C)						
Tube O.D. on flanged shaft drive side [mm]	SD32	3				–		
	SD42	4				–		
	SD48	–				4		
	SD62	–				6		
	SD64	–				6		
Push-in fittings for connection to consuming device [mm]	SD32	QS-...-3 for tube O.D. 3 mm					–	
	SD42	QS-...-4 for tube O.D. 4 mm					–	
	SD48	–					QS-...-4 for tube O.D. 4 mm	
	SD62	–					QS-...-6 for tube O.D. 6 mm	
	SD64	–					QS-...-6 for tube O.D. 6 mm	

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

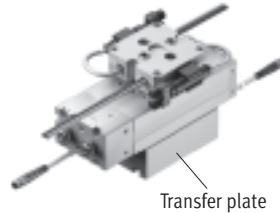
Energy through-feed

DRQD-...-E422



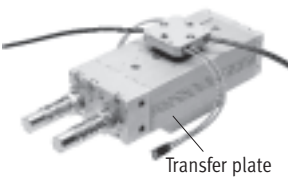
- For piston \varnothing 16/20
- Swivel angles of up to 180° are possible
- 1 DUO tube with O.D. 4 mm
- 1 4-pin cable to 2 3-pin cables

DRQD-...-E444



- For piston \varnothing 25/32
- Swivel angles of up to 180° are possible
- 2 DUO tubes each with O.D. 4 mm
- 2 4-pin cables to 4 3-pin cables

DRQD-...-E644



- For piston \varnothing 40/50
- Swivel angles of up to 180° are possible
- 2 DUO tubes each with O.D. 6 mm
- 4 3-pin cables

Technical data

Piston \varnothing		16	20	25	32	40	50
Number of DUO tubes	E422	1		-			
	E444	-		2	-		
	E644	-				2	
Standard nominal flow rate (per tube) [l/min]	E422	min. 130		-			
	E444	-		min. 130		-	
	E644	-				min. 250	
Theoretical air consumption per line at 6 bar [cm ³]	E422	9.5		-			
	E444	-		9.5		-	
	E644	-				24.4	
Operating pressure as a function of ambient temperature [bar]			0 ... 10 (at -10 ... +30 °C)				
			0 ... 9 (at +30 ... +40 °C)				
			0 ... 7 (at +40 ... +60 °C)				
Tube O.D. on flanged shaft drive side [mm]	E422	4		-			
	E444	-		4		-	
	E644	-				6	
Push-in fittings for connection to consuming device [mm]	E422	QS-...-4 for tube O.D. 4 mm		-			
	E444	-		QS-...-4 for tube O.D. 4 mm		-	
	E644	-				QS-...-6 for tube O.D. 6 mm	

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

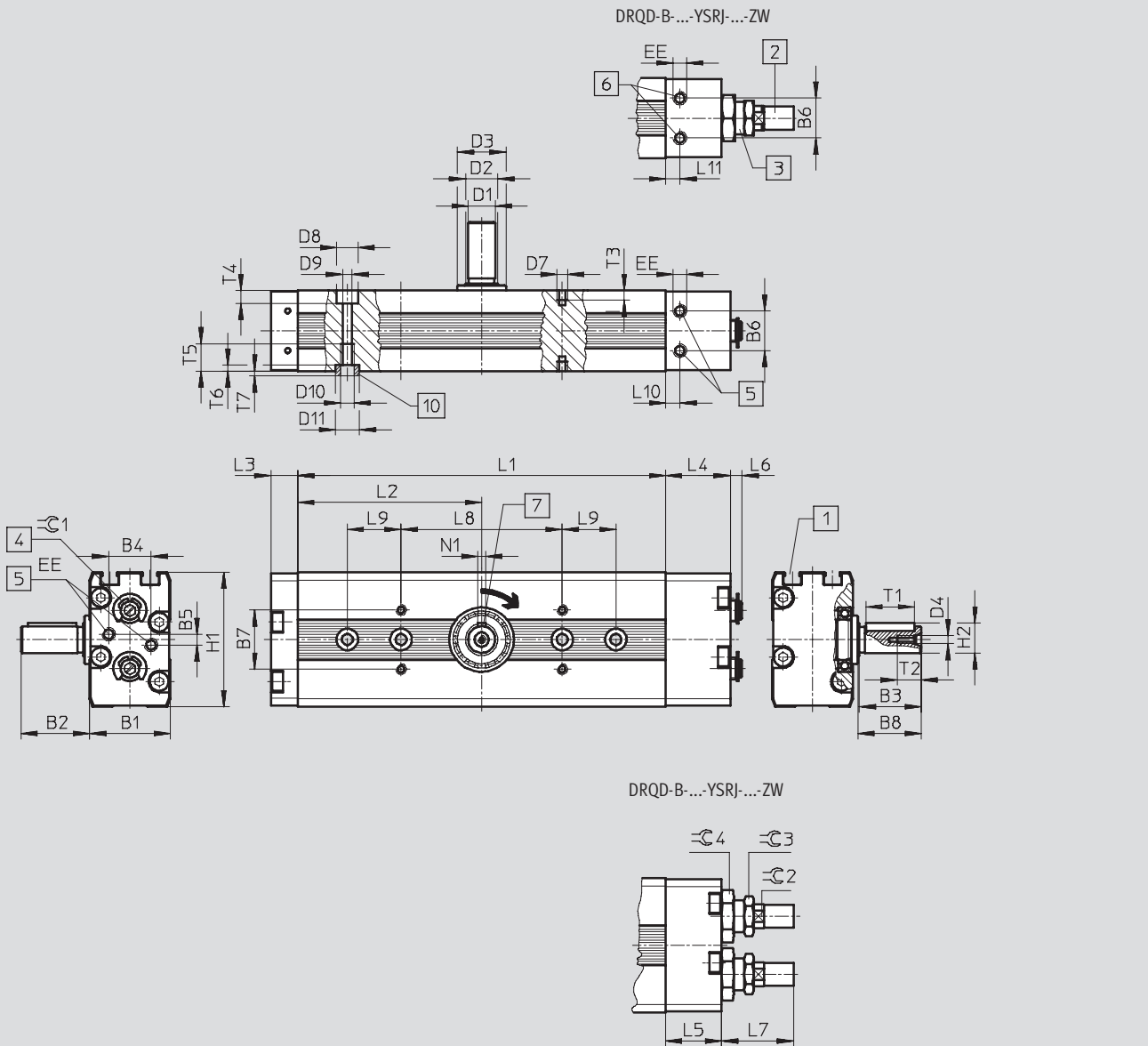
Technical data

FESTO

Dimensions

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ZW – Spigot shaft



- | | | | |
|---|---|---|---|
| <p>1 T-slots for proximity sensors SME/SMT-8</p> <p>2 Self-adjusting shock absorber for end-position cushioning</p> | <p>3 Adjustable sleeve for end-position adjustment for type DRQD-B-...-YSRJ</p> <p>4 Socket head screw for end-position adjustment with integral regulating screw for end-position cushioning</p> | <p>5 Variant PPVJ: both supply ports on one end cap, optionally at front or side</p> <p>6 Variant YSRJ: Both supply ports on one end cap, front side only</p> | <p>7 Woodruff key position at 0°</p> <p>10 Centring sleeves (2 included in scope of delivery)</p> |
|---|---|---|---|

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B8	D1 ∅ g6	D2 ∅	D3 ∅	D4	D7	D8 ∅ H13
16	90	30	25.5	23	17.8	4	14.8	22	23.5	10	12	18	M3	M4	8
	180														
	360														
20	90	36	32.5	30	21.8	4	19.8	26	30.5	12	15	24	M4	M4	8
	180														
	360														
25	90	42	42.5	40	24.8	4	24.8	30	40.5	16	20	30	M5	M5	10
	180														
	360														
32	90	51	52.5	50	29.8	2	29.8	36	50.5	20	25	35	M6	M5	10
	180														
	360														

∅ [mm]	Swivel angle [°]	D9 ∅	D10	D11 ∅ H7	EE	H1	H2	L1	L2	L3	L4	L5	L6		L7		L8 ±0.03
													min.	max.	min.	max.	
16	90	4.2	M5	9	M5	50	11.2	71	35.5	10	24	20.8	1.7	5.7	23.4	28.2	60
	180							93	46.5								
	360							137	68.5								
20	90	4.2	M5	9	M5	56	13.5	78.4	39.2	10	31.5	27	2.4	7	28.6	35.9	60
	180							104.8	52.4								
	360							157.6	78.8								
25	90	5.3	M6	9	M5	67	18	91.2	45.6	11	36.5	33	2.6	8.9	42	50.2	60
	180							124	62								
	360							189.2	94.6								
32	90	5.3	M6	9	G $\frac{3}{8}$	79	22.5	114.8	57.4	13	39	39	4.3	11.8	59.4	70.1	80
	180							155.6	77.8								
	360							237.4	118.7								

∅ [mm]	Swivel angle [°]	L9 ±0.03	L10	L11	N1 P9	T1	T2	T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4
16	90	-	7.6	5.3	3	18.1	9	3.5	5	10	2	2	4	9	13	17
	180	-														
	360	20														
20	90	-	8	5	4	25.1	10	3.5	5	12	2	2	7	11	15	19
	180	-														
	360	20														
25	90	-	11	5	5	36.1	12.5	5	6	12	2	2	7	15	19	24
	180	-														
	360	20														
32	90	-	13.1	8	6	45.1	16	5	6	14	2	2	8	20	27	32
	180	20														
	360	20														

Semi-rotary drives DRQD-40 ... 50, twin-pistons

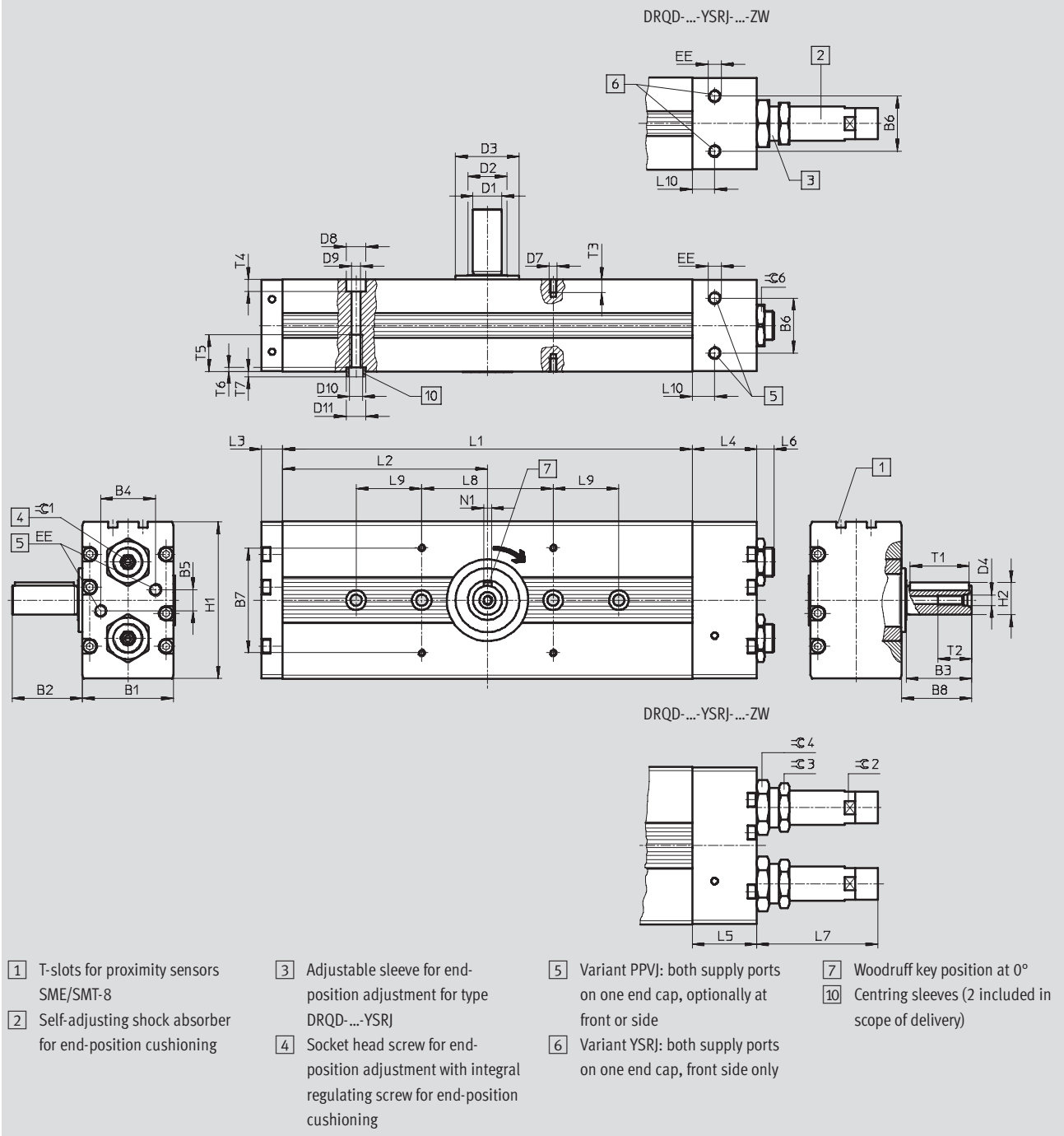
Technical data

FESTO

Dimensions

Download CAD data → www.festo.com

ZW – Spigot shaft



Semi-rotary drives DRQD-40 ... 50, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B8	D1 ∅ g6	D2 ∅	D3 ∅	D4	D7	D8 ∅ H13	D9 ∅
40	90	70	53.5	50	42	4	42	80	50.5	22	30	48.5	M8	M6	15	8.5
	180															
	360															
50	90	86	63.5	60	50	16	50	80	60.9	28	38	58.5	M12	M6	15	8.5
	180															
	360															

∅ [mm]	Swivel angle [°]	D10	D11 ∅ H7	EE	H1	H2	L1	L2	L3	L4	L5	L6		L7		L8 ±0.03
												min.	max.	min.	max.	
40	90	M10	15	G $\frac{1}{8}$	120	24.5	146.8	73.4	16	49	41.5	5	14.6	85.1	96.4	100
	180						201.8	100.9								
	360						311.8	155.9								
50	90	M10	15	G $\frac{1}{4}$	144	31	191.4	95.7	18	64	55	8	20.7	107.8	120.6	100
	180						262.8	131.4								
	360						405.8	202.9								

∅ [mm]	Swivel angle [°]	L9 ±0.03	L10	N1 P9	T1	T2 +2	T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C6
40	90	-	17	6	45.1	26	10	10	28	3	3	10	24	32	36	27
	180	-														
	360	50														
50	90	-	21.2	8	56.1	28	10	11	28	3	3	14	28	36	46	41
	180	50														
	360	100														

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

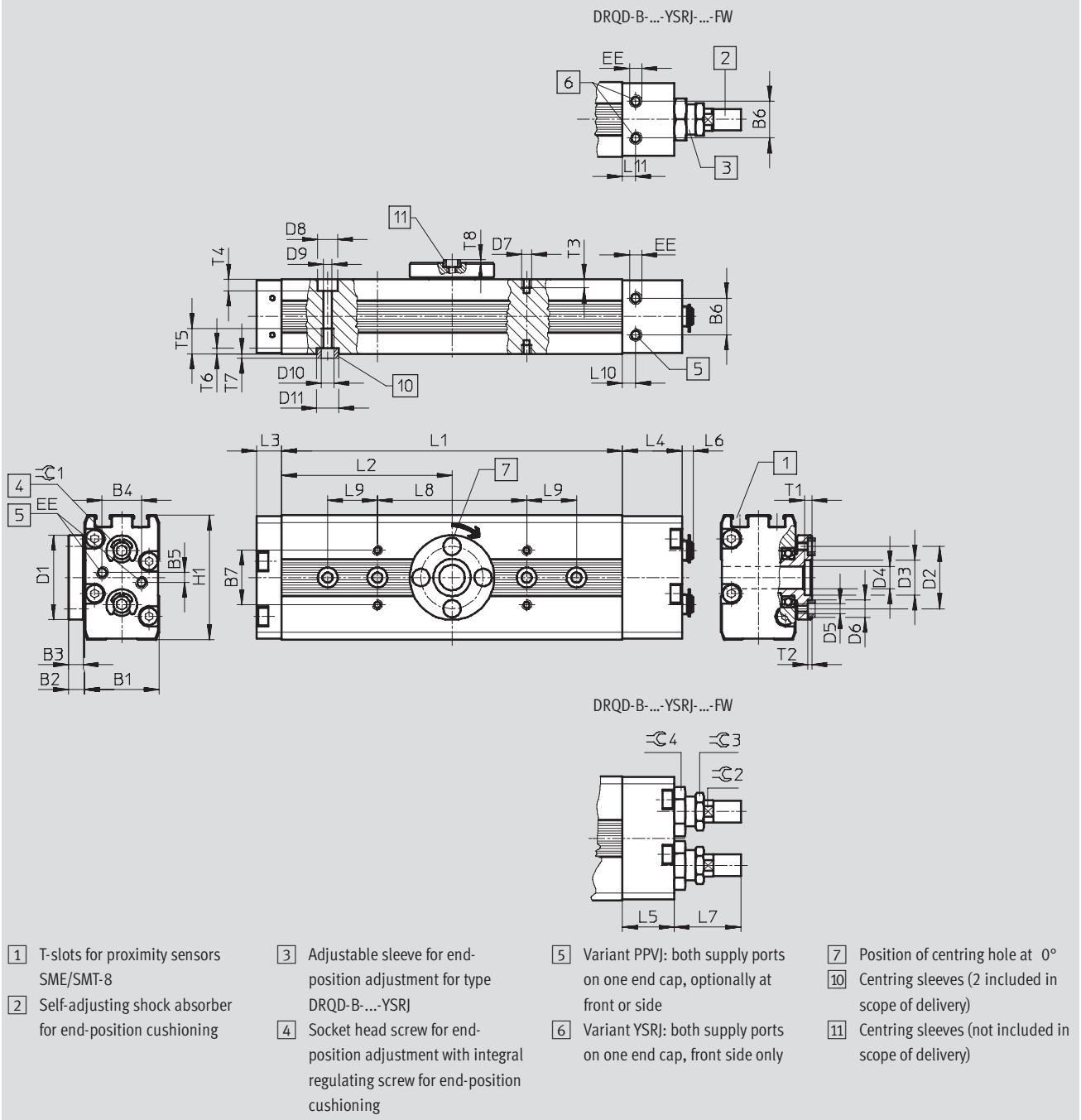
Technical data

FESTO

Dimensions

Download CAD data → www.festo.com

FW – Flanged shaft



Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	D1 ∅	D2 ∅ ±0.025	D3 ∅ H8	D4 ∅	D5	D6 ∅ H7	D7	D8 ∅ H13
16	90	30	6.5	6	17.8	4	14.8	22	34	25	14	9	M4	7	M4	8
	180															
	360															
20	90	36	6.5	6	21.8	4	19.8	26	38	28	16	11	M4	7	M4	8
	180															
	360															
25	90	42	9.5	9	24.8	4	24.8	30	48	34	16	12	M6	9	M5	10
	180															
	360															
32	90	51	9.5	9	29.8	2	29.8	36	58	45	19	14	M6	9	M5	10
	180															
	360															

∅ [mm]	Swivel angle [°]	D9 ∅	D10	D11 ∅ H7	EE	H1	L1	L2	L3	L4	L5	L6		L7		L8 ±0.03
												min.	max.	min.	max.	
16	90	4.2	M5	9	M5	50	71	35.5	10	24	20.8	1.7	5.7	23.4	28.2	60
	180						93	46.5								
	360						137	68.5								
20	90	4.2	M5	9	M5	56	78.4	39.2	10	31.5	27	2.4	7	28.6	35.9	60
	180						104.8	52.4								
	360						157.6	78.8								
25	90	5.3	M6	9	M5	67	91.2	45.6	11	36.5	33	2.6	8.9	42	50.2	60
	180						124	62								
	360						189.2	94.6								
32	90	5.3	M6	9	G $\frac{1}{8}$	79	114.8	57.4	13	39	39	4.3	11.8	59.4	70.1	80
	180						155.6	77.8								
	360						237.4	118.7								

∅ [mm]	Swivel angle [°]	L9 ±0.03	L10	L11	T1	T2	T3	T4	T5	T6	T7	T8	≈C1	≈C2	≈C3	≈C4
16	90	-	7.6	5.3	3	1.6	3.5	5	10	2	2	1.4	4	9	13	17
	180	-														
	360	20														
20	90	-	8	5	3	1.6	3.5	5	12	2	2	1.4	7	11	15	19
	180	-														
	360	20														
25	90	-	11	5	3	2	5	6	12	2	2	2	7	15	19	24
	180	-														
	360	20														
32	90	-	13.1	8	3	2	5	6	14	2	2	2	8	20	27	32
	180	20														
	360	20														

Semi-rotary drives DRQD-40 ... 50, twin-pistons

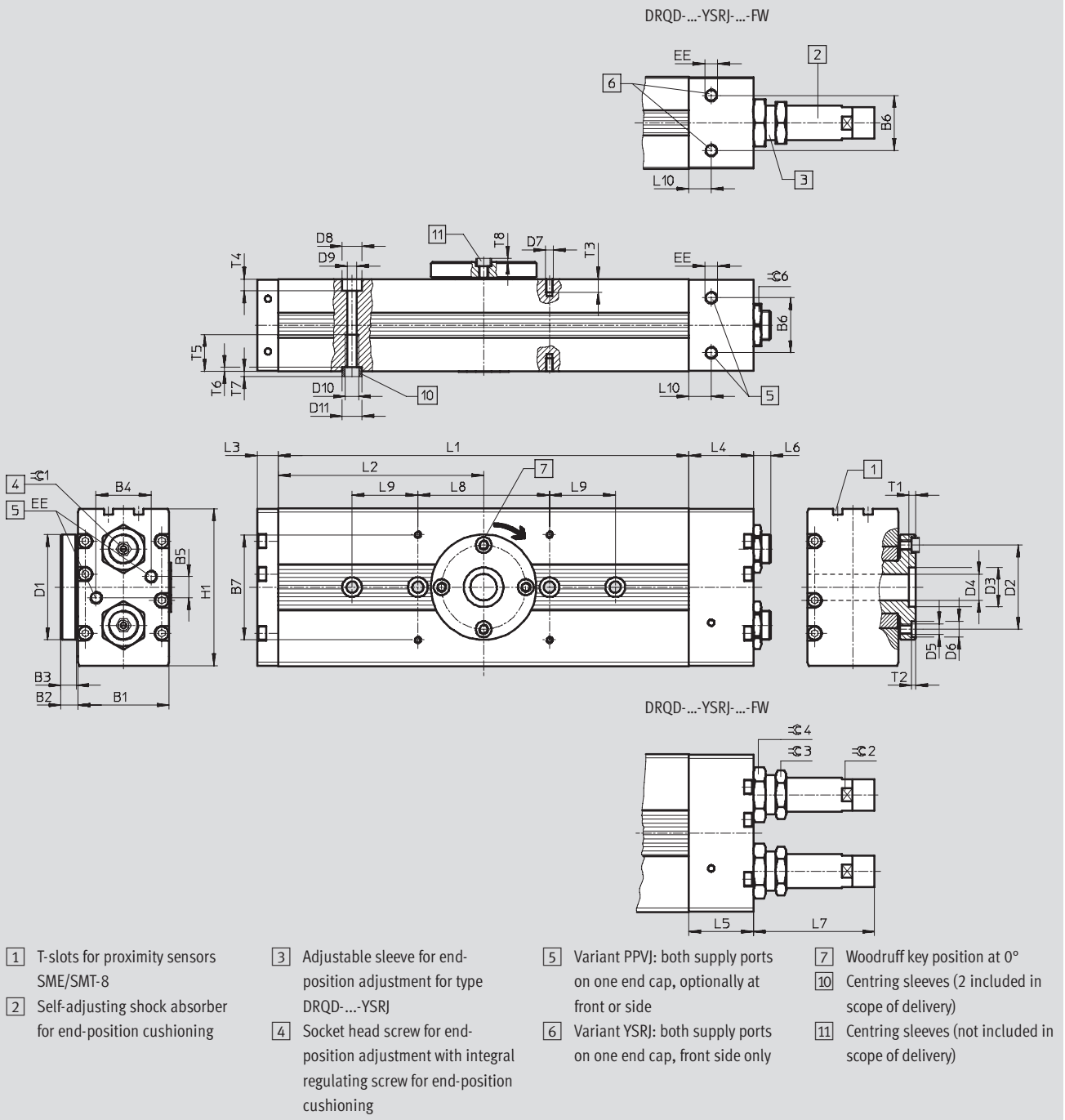
Technical data

FESTO

Dimensions

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FW – Flanged shaft



Semi-rotary drives DRQD-40 ... 50, twin-pistons



Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	D1 ∅	D2 ∅ ±0.025	D3 ∅ H7	D4	D5	D6 ∅ H7	D7	D8 ∅ H13
40	90	70	13	12	42	4	42	80	80	64	30	20	M8	12	M6	15
	180															
	360															
50	90	86	13	12	50	16	50	80	85	64	30	24	M8	12	M6	15
	180															
	360															

∅ [mm]	Swivel angle [°]	D9 ∅	D10	D11 ∅ H7	EE	H1	L1	L2	L3	L4	L5	L6		L7	
												min.	max.	min.	max.
40	90	8.5	M10	15	G $\frac{1}{8}$	120	146.8	73.4	16	49	41.5	5	14.6	85.1	96.4
	180						201.8	100.9							
	360						311.8	155.9							
50	90	8.5	M10	15	G $\frac{1}{4}$	144	191.4	95.7	18	64	55	8	20.7	107.8	120.6
	180						262.8	131.4							
	360						405.8	202.9							

∅ [mm]	Swivel angle [°]	L8 ±0.03	L9 ±0.03	L10	T1	T2	T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C6
180	-															
360	50															
50	90	100	-	21.2	4	2.7	10	11	28	3	3	14	28	36	46	41
	180		50													
	360		100													

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

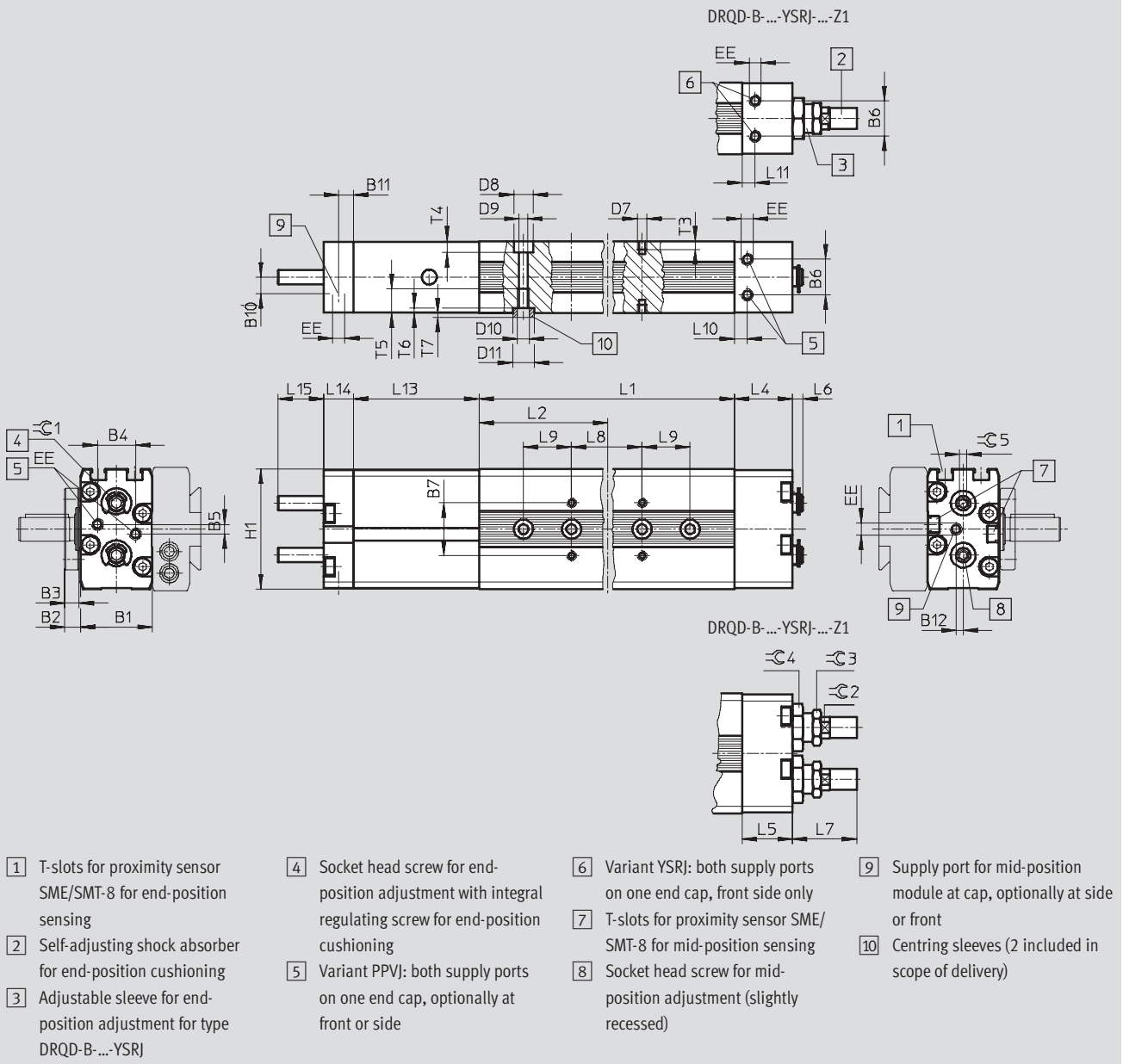
Technical data



Dimensions

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Z1 – Intermediate position module (energy through-feed is optional)



Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B10	B11	B12	D7	D8 ∅ H13	D9 ∅	D10	D11 ∅ H7
16	90	30	6.5	6	17.8	4	14.8	22	6.4	4.5	3	M4	8	4.2	M5	9
	180															
20	90	36	6.5	6	21.8	4	19.8	26	6.5	4.5	5.6	M4	8	4.2	M5	9
	180															
25	90	42	9.5	9	24.8	4	24.8	30	9.1	6.9	8.2	M5	10	5.3	M6	9
	180															
32	90	51	9.5	9	29.8	2	29.8	36	9	8	9	M5	10	5.3	M6	9
	180															

∅ [mm]	Swivel angle [°]	EE	H1	L1	L2	L4	L5	L6		L7		L8 ±0.03	L9 ±0.03	L10	L11
								min.	max.	min.	max.				
16	90	M5	50	71	35.5	24	20.8	1.7	5.7	23.4	28.2	60	-	7.6	5.3
	180			93	46.5								-		
20	90	M5	56	78.4	39.2	31.5	27	2.4	7	28.6	35.9	60	-	8	5
	180			104.8	52.4								-		
25	90	M5	67	91.2	45.6	36.5	33	2.6	8.9	42	50.2	60	-	11	5
	180			124	62								-		
32	90	G $\frac{1}{8}$	79	114.8	57.4	39	39	4.3	11.8	59.4	70.1	80	-	13.1	8
	180			155.6	77.8								20		

∅ [mm]	Swivel angle [°]	L13	L14	L15		T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C5
				min.	max.										
16	90	52.2	12.3	0	19.1	3.5	5	10	2	2	4	9	13	17	3
	180														
20	90	55.4	12.3	0	21.8	3.5	5	12	2	2	7	11	15	19	3
	180														
25	90	62.1	15	0	26	5	6	12	2	2	7	15	19	24	4
	180														
32	90	68.2	15.5	0	31.5	5	6	14	2	2	8	20	27	32	4
	180														

Semi-rotary drives DRQD-40 ... 50, twin-pistons

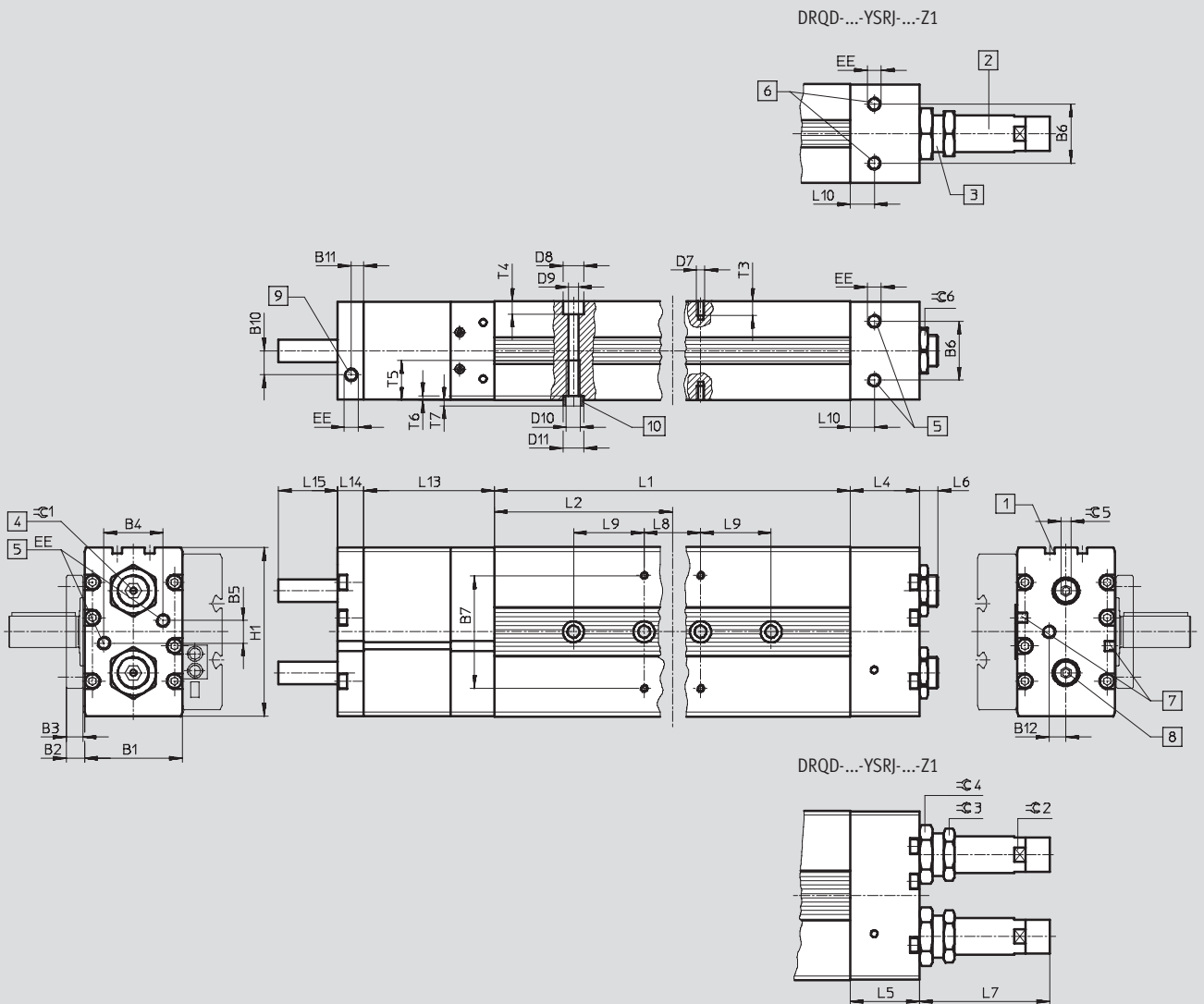
Technical data

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Dimensions

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Z1 – Intermediate position module (energy through-feed is optional)



- | | | | |
|---|--|--|---|
| <p>1 T-slots for proximity sensor SME/SMT-8 for end-position sensing</p> <p>2 Self-adjusting shock absorber for end-position cushioning</p> <p>3 Adjustable sleeve for end-position adjustment for type DRQD-...-YSRJ</p> | <p>4 Socket head screw for end-position adjustment with integral regulating screw for end-position cushioning</p> <p>5 Variant PPVJ: both supply ports on one end cap, optionally at front or side</p> | <p>6 Variant YSRJ: both supply ports on one end cap, front side only</p> <p>7 T-slots for proximity sensor SME/SMT-8 for mid-position sensing</p> <p>8 Socket head screw for mid-position adjustment (slightly recessed)</p> | <p>9 Supply port for mid-position module at cap, optionally at side or front</p> <p>10 Centring sleeves (2 included in scope of delivery)</p> |
|---|--|--|---|

Semi-rotary drives DRQD-40 ... 50, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B10	B11	B12	D7	D8 ∅ H13	D9 ∅	D10
40	90	70	13	12	42	4	42	80	92.5	9	12	M6	15	8.5	M10
	180														
	360														
50	90	86	13	12	50	16	50	80	105.7	9	14	M6	15	8.5	M10
	180														
	360														

∅ [mm]	Swivel angle [°]	D11 ∅ H7	EE	H1	L1	L2	L4	L5	L6		L7		L8 ±0.03	L9 ±0.03	L10
									min.	max.	min.	max.			
40	90	15	G $\frac{1}{8}$	120	146.8	73.4	49	41.5	5	14.6	85.1	96.4	100	-	17
	180				201.8	100.9								-	
	360				311.8	155.9								50	
50	90	15	G $\frac{1}{4}$	144	191.4	95.7	64	55	8	20.7	107.8	120.6	100	-	21.2
	180				262.8	131.4								50	
	360				405.8	202.9								100	

∅ [mm]	Swivel angle [°]	L13	L14	L15		T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C5	≈C6
				min.	max.											
40	90	92.5	18.5	0	41.95	10	10	28	3	3	10	24	32	36	7	27
	180															
	360															
50	90	105.7	20.5	0	52.95	10	11	28	3	3	14	28	36	46	7	41
	180															
	360															

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

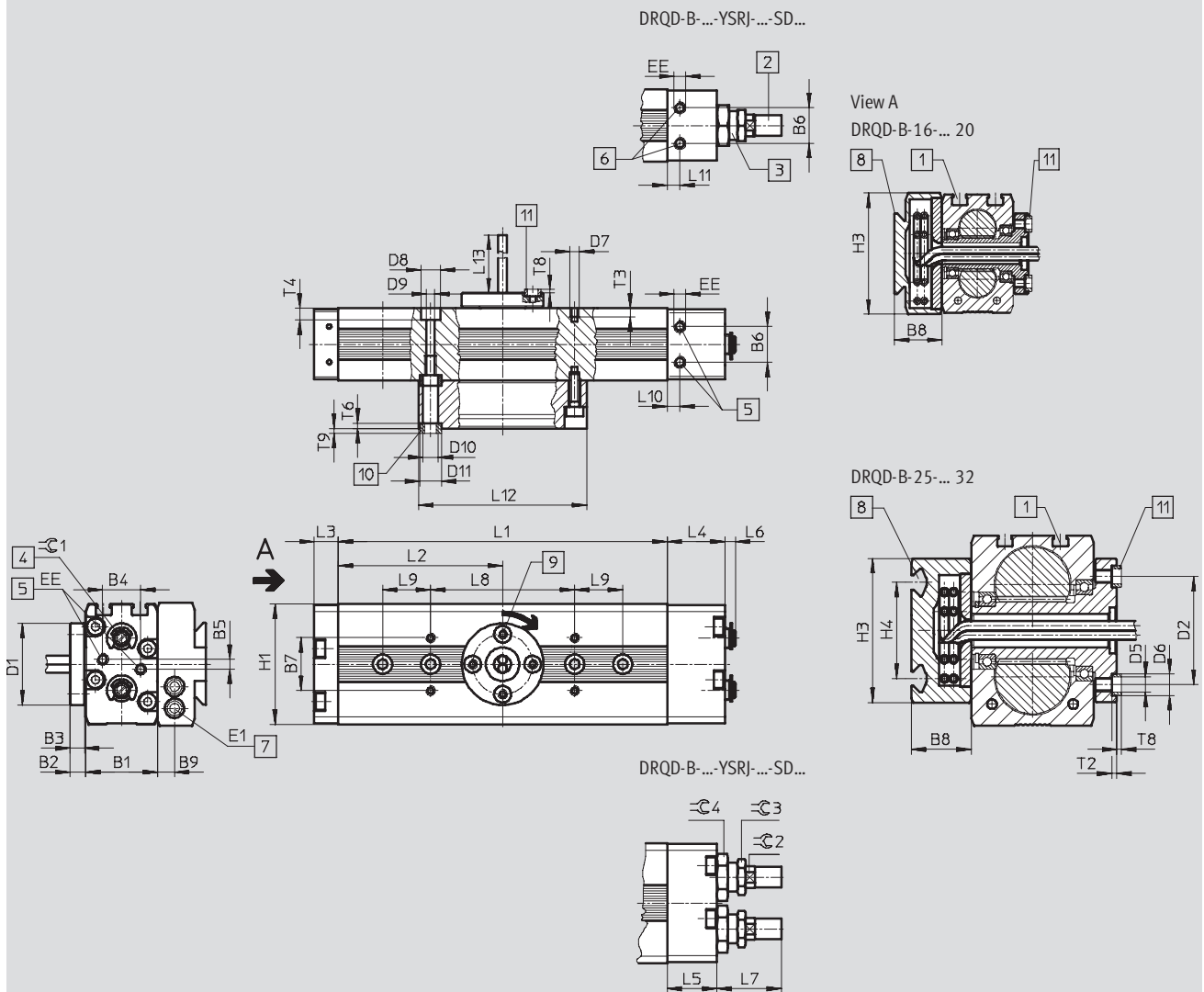
Technical data

FESTO

Dimensions

FW-SD – Energy through-feed

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- | | | | |
|---|--|--|--|
| <p>1 T-slots for proximity sensors SME/SMT-8</p> <p>2 Self-adjusting shock absorber for end-position cushioning</p> <p>3 Adjustable sleeve for end-position adjustment for type DRQD-B-...-YSRJ</p> | <p>4 Socket head screw for end-position adjustment with integral regulating screw for end-position cushioning</p> <p>5 Variant PPVJ: both supply ports on one end cap, optionally at front or side</p> | <p>6 Variant YSRJ: both supply ports on one end cap, front side only</p> <p>7 Supply port for energy through-feed</p> <p>8 Mounting option via dovetail profile (for \varnothing 16 to 20 mm) or profile slot nut (grid dimensions 40 mm for \varnothing 25 to 32 mm) → 60</p> | <p>9 Position of designated centring hole at 0°</p> <p>10 Centring sleeves (2 included in scope of delivery) → 60</p> <p>11 Centring sleeves (not included in scope of delivery)</p> |
|---|--|--|--|

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B8	B9	D1 ∅	D2 ∅ ±0.025	D5	D6 ∅ H7	D7	D8 ∅ H13	D9 ∅
16	90	30	6.5	6	17.8	4	14.8	22	20	7	34	25	M4	7	M4	8	4.2
	180																
	360																
20	90	36	6.5	6	21.8	4	19.8	26	20	7	38	28	M4	7	M4	8	4.2
	180																
	360																
25	90	42	9.5	9	24.8	4	24.8	30	25	7	48	34	M6	9	M5	10	5.3
	180																
	360																
32	90	51	9.5	9	29.8	2	29.8	36	25	7	58	45	M6	9	M5	10	5.3
	180																
	360																

∅ [mm]	Swivel angle [°]	D10 ∅ H13	D11 ∅ H7	EE	E1 ∅	H1	H3	H4	L1	L2	L3	L4	L5	L6		L7	
														min.	max.	min.	max.
16	90	5.5	9	M5	4	50	51	-	71	35.5	10	24	20.8	1.7	5.7	23.4	28.2
	180								93	46.5							
	360								137	68.5							
20	90	5.5	9	M5	4	56	51	-	78.4	39.2	10	31.5	27	2.4	7	28.6	35.9
	180								104.8	52.4							
	360								157.6	78.8							
25	90	6.6	9	M5	4	67	60	40	91.2	45.6	11	36.5	33	2.6	8.9	42	50.2
	180								124	62							
	360								189.2	94.6							
32	90	6.6	9	G $\frac{1}{8}$	4	79	60	40	114.8	57.4	13	39	39	4.3	11.8	59.4	70.1
	180								155.6	77.8							
	360								237.4	118.7							

∅ [mm]	Swivel angle [°]	L8 ±0.03	L9 ±0.03	L10	L11	L12	L13 min.	T2	T3	T4	T6	T8	T9	≈C1	≈C2	≈C3	≈C4
16	90	60	-	7.6	5.3	72	255	1.6	3.5	5	2.1	1.4	2	4	9	13	17
	180		-														
	360		20														
20	90	60	-	8	5	72	250	1.6	3.5	5	2.1	1.4	2	7	11	15	19
	180		-														
	360		20														
25	90	60	-	11	5	95	240	2	5	6	2.1	2	2	7	15	19	24
	180		-														
	360		20														
32	90	80	-	13.1	8	95	230	2	5	6	2.1	2	2	8	20	27	32
	180		20														
	360		20														

Semi-rotary drives DRQD-40 ... 50, twin-pistons

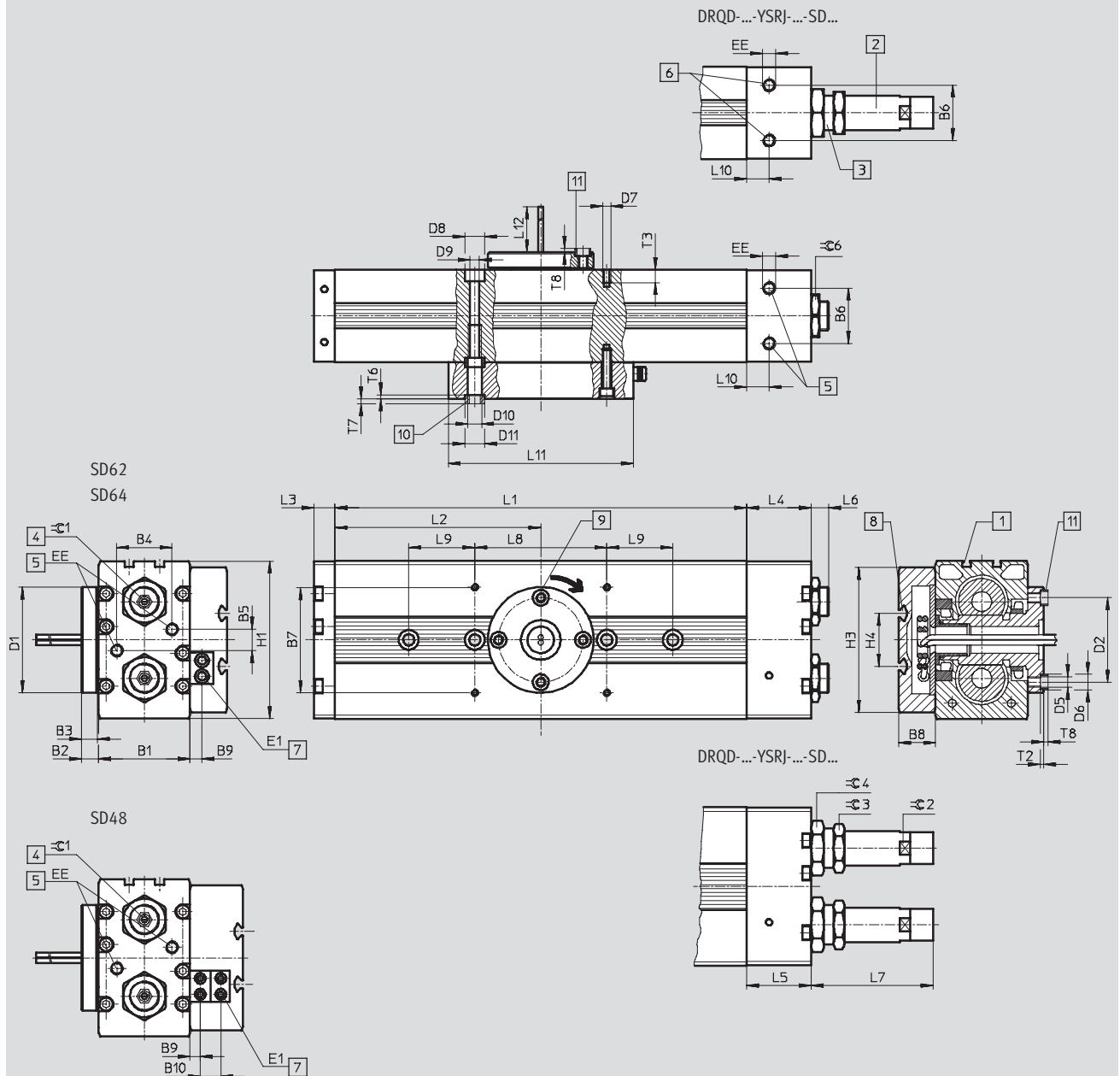
Technical data

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Dimensions

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FW-SD – Energy through-feed



- | | | | |
|---|--|--|--|
| <p>1 T-slots for proximity sensors SME/SMT-8</p> <p>2 Self-adjusting shock absorber for end-position cushioning</p> <p>3 Adjustable sleeve for end-position adjustment for type DRQD-...-YSRJ</p> | <p>4 Socket head screw for end-position adjustment with integral regulating screw for end-position cushioning</p> <p>5 Variant PPVJ: both supply ports on one end cap, optionally at front or side</p> | <p>6 Variant YSRJ: both supply ports on one end cap, front side only</p> <p>7 Supply port for energy through-feed</p> <p>8 Mounting option via profile slot nut (grid dimensions 40 mm) → 60</p> | <p>9 Position of designated centring hole at 0°</p> <p>10 Centring sleeves (2 included in scope of delivery) → 60</p> <p>11 Centring sleeves (not included in scope of delivery)</p> |
|---|--|--|--|

Semi-rotary drives DRQD-40 ... 50, twin-pistons

Technical data

∅ [mm]	Swivel angle [°]	Variant	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	D1 ∅	D2 ∅ ±0.05	D3 ∅ H7	D4 ∅	D5	D6 ∅ H7	D7	D8 ∅ H13
40	90	SD62/SD64	70	13	12	42	4	42	80	28	9	–	80	64	30	20	M8	12	M6	15
		SD48								40	7.75	15.5								
	180	SD62/SD64	70	13	12	42	4	42	80	28	9	–	80	64	30	20	M8	12	M6	15
		SD48								40	7.75	15.5								
	360	SD62/SD64	70	13	12	42	4	42	80	28	9	–	80	64	30	20	M8	12	M6	15
		SD48								40	7.75	15.5								
50	90	SD62/SD64	86	13	12	50	16	50	80	28	9	–	85	64	30	24	M8	12	M6	15
		SD48								40	7.75	15.5								
	180	SD62/SD64	86	13	12	50	16	50	80	28	9	–	85	64	30	24	M8	12	M6	15
		SD48								40	7.75	15.5								
	360	SD62/SD64	86	13	12	50	16	50	80	28	9	–	85	64	30	24	M8	12	M6	15
		SD48								40	7.75	15.5								

∅ [mm]	Swivel angle [°]	Variant	D9 ∅	D10 ∅	D11 ∅ H7	EE	E1	H1	H3	L1	L2	L3	L4	L5	L6		L7	
															min.	max.	min.	max.
40	90	SD62/SD64	8.5	M10	15	G1/8	6	120	110	146.8	73.4	16	49	41.5	5	14.6	85.1	96.4
		SD48																
	180	SD62/SD64	8.5	M10	15	G1/8	6	120	110	201.8	100.9	16	49	41.5	5	14.6	85.1	96.4
		SD48																
	360	SD62/SD64	8.5	M10	15	G1/8	6	120	110	311.8	155.9	16	49	41.5	5	14.6	85.1	96.4
		SD48																
50	90	SD62/SD64	8.5	M10	15	G1/4	6	144	110	191.4	95.7	18	64	55	8	20.7	107.8	120.6
		SD48																
	180	SD62/SD64	8.5	M10	15	G1/4	6	144	110	262.8	131.4	18	64	55	8	20.7	107.8	120.6
		SD48																
	360	SD62/SD64	8.5	M10	15	G1/4	6	144	110	405.8	202.9	18	64	55	8	20.7	107.8	120.6
		SD48																

∅ [mm]	Swivel angle [°]	Variant	L8	L9	L10	L11	L12	T1	T2	T3	T4	T5	T6	T7	T8	≈C1	≈C2	≈C3	≈C4	≈C6
			±0.03	±0.03					min.											
40	90	SD62/SD64	100	–	17	140	42	4	2.7	10	10	28	3	3	2.3	10	24	32	36	27
		SD48																		
	180	SD62/SD64	100	–	17	140	42	4	2.7	10	10	28	3	3	2.3	10	24	32	36	27
		SD48																		
	360	SD62/SD64	100	50	17	140	42	4	2.7	10	10	28	3	3	2.3	10	24	32	36	27
		SD48																		
50	90	SD62/SD64	100	–	21.2	140	26	4	2.7	10	11	28	3	3	2.3	14	28	36	46	41
		SD48																		
	180	SD62/SD64	100	50	21.2	140	26	4	2.7	10	11	28	3	3	2.3	14	28	36	46	41
		SD48																		
	360	SD62/SD64	100	100	21.2	140	26	4	2.7	10	11	28	3	3	2.3	14	28	36	46	41
		SD48																		

Semi-rotary drives DRQD-B-16 ... 20, twin-pistons

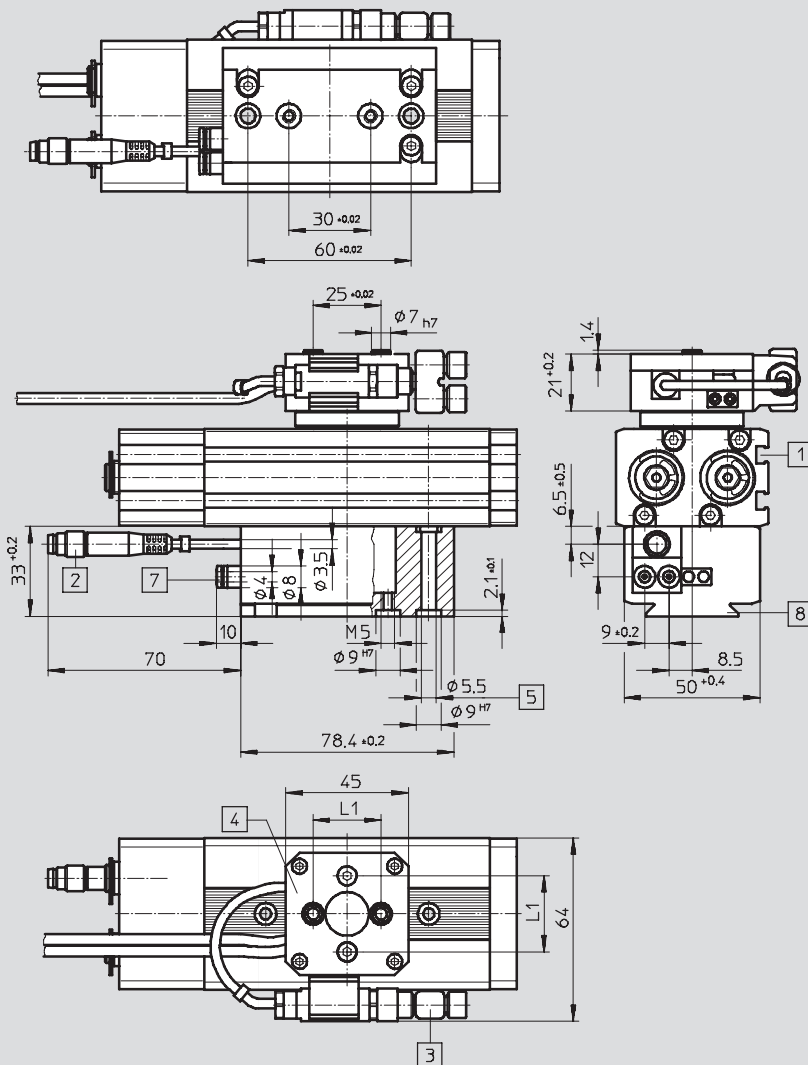
Technical data

FESTO

Dimensions

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FW E422 – Energy through-feed



L1
for $\varnothing 16$: $25 \pm 0,02$ mm
for $\varnothing 20$: $28 \pm 0,02$ mm

- 1 T-slots for proximity sensors
SME/SMT-8
- 2 Plug M8x1, 4-pin
- 3 Socket M8x1 for proximity sensor
SME/SMT

- 4 Output plate can be repositioned
by 90°
- 5 Screw-through option with screw
M4

- 7 Supply port for energy through-
feed for tubing O.D. 4 mm
- 8 Mounting option via dovetail
connection

Semi-rotary drives DRQD-B-25 ... 32, twin-pistons

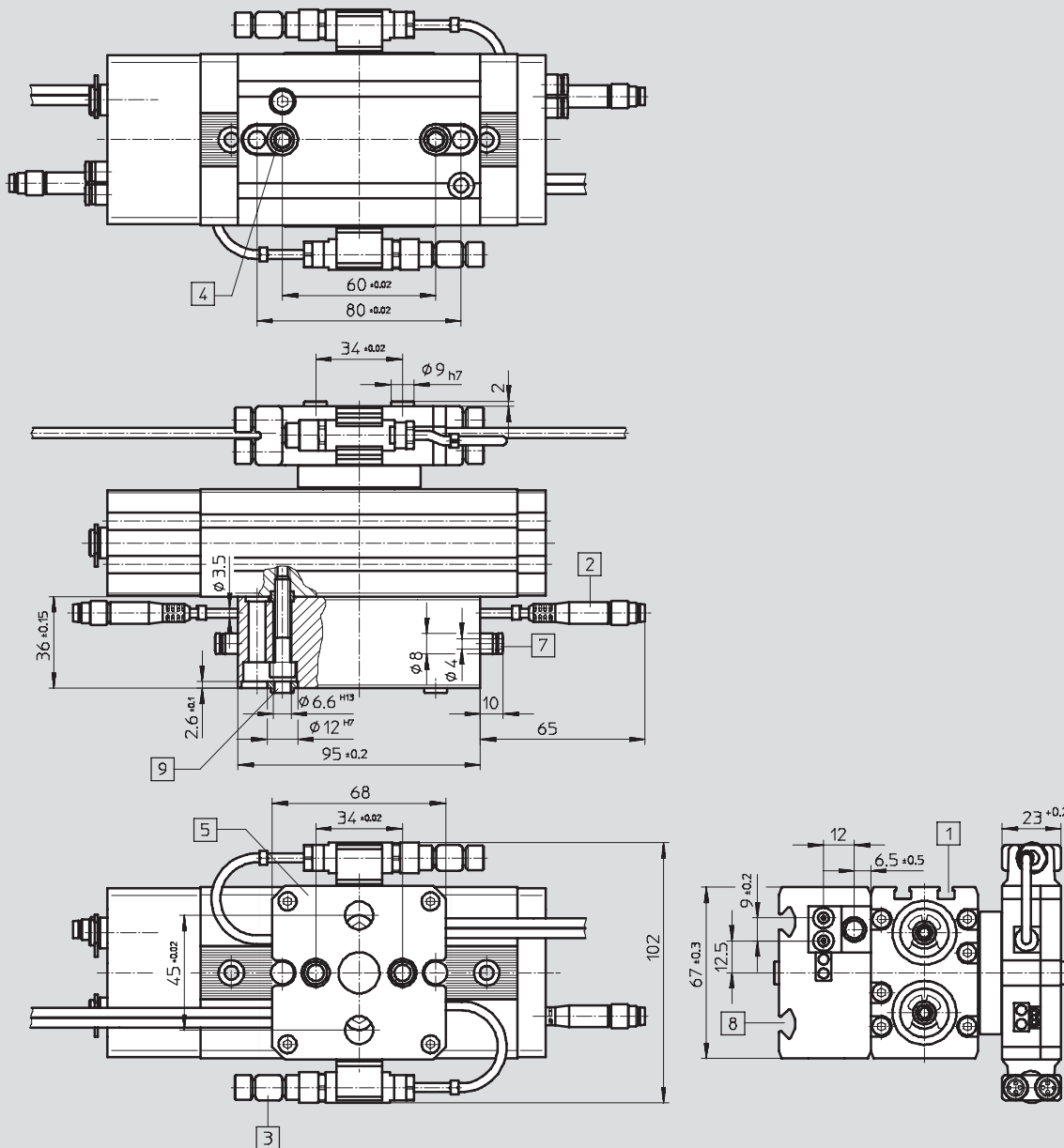
Technical data

FESTO

Dimensions

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FW-E444 – Energy through-feed



- | | | | |
|--|---|--|--|
| 1 T-slots for proximity sensors SME/SMT-8 | 4 Mounting via through-holes possible with screw M5 (retaining screws must be removed beforehand) | 7 Supply port for energy through-feed for tubing O.D. 4 mm | 9 Centring sleeves (2 pieces included in scope of delivery) → 60 |
| 2 Plug M8x1, 4-pin | 5 Centring hole can be repositioned by 90° | 8 Mounting option via profile slot nut | |
| 3 Socket M8x1 for proximity sensor SME/SMT | | | |

Semi-rotary drives DRQD-40 ... 50, twin-pistons

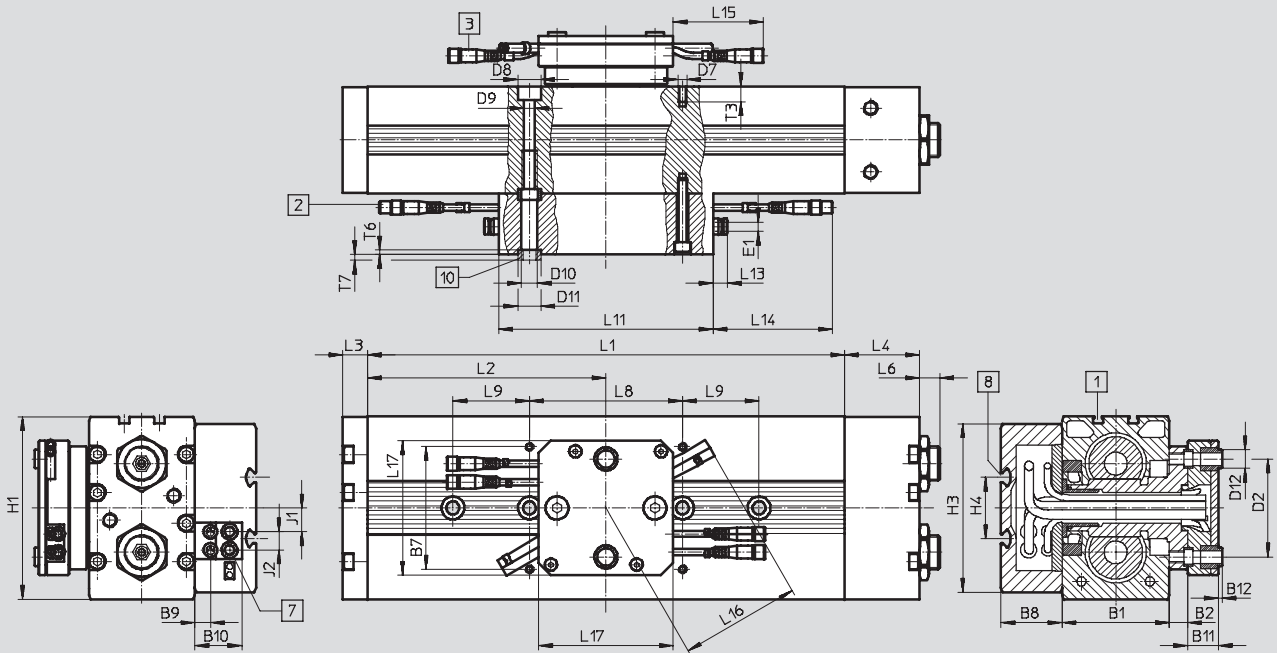
Technical data



Dimensions

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FW-E644 – Energy through-feed





- 1 T-slots for proximity sensors SME/SMT-8
- 2 Plug M8x1
- 3 Socket M8x1
- 7 Supply port for energy through-feed for tubing O.D. 6 mm
- 8 Mounting option via profile slot nut (grid dimensions 40 mm) → 60
- 10 Centring sleeves (2 pieces included in scope of delivery) → 60

∅	Swivel angle	B1	B2	B7	B8	B9	B10	B11	B12	D2	D7	D8	D9	D10	D11	D12	E1	H1	H3	
[mm]	[°]	±0.2	+0.4 -0.3		+0.2 -0.1			±0.2		±0.2	M6	H13		∅	∅	∅	∅			
40	90																			
	180	70	13	80	40	9.5	12.5	20	2.5	64	M6	15	8.5	M10	15	12	6	120	110	
	360																			
50	90																			
	80	86	13	80	40	9.5	12.5	20	2.5	64	M6	15	8.5	M10	15	12	6	144	110	
	360																			

∅	Swivel angle	H4	L1	L2	L3	L4	L6		L8	L9	L11	L13	L14	L15	L16	L17	T3	T6	T7	
[mm]	[°]						min.	max.	±0.03	±0.03			ap-prox.	min.	min.			±0.15		
40	90		146.8	73.4						-										
	180	40	201.8	100.9	16	49	5	14.6	100	-	140	9.5	64	150	75	88	10	3	3	
	360		311.8	155.9						50										
50	90		191.4	95.7						-										
	180	40	262.8	131.4	18	64	5	20.7	100	50	140	9.5	65	130	75	88	10	3	3	
	360		405.8	202.9						50										

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Ordering data – Standard types				
DRQD	∅ [mm]	Swivel angle [°]	Part No.	Type
PPVJ – Adjustable end-position cushioning				
	AL – Connection on left			
	16	180	563 341	DRQD-B-16-180-PPVJ-A-AL-FW
	20		563 342	DRQD-B-20-180-PPVJ-A-AL-FW
	25		563 343	DRQD-B-25-180-PPVJ-A-AL-FW
	32		563 344	DRQD-B-32-180-PPVJ-A-AL-FW
	AR – Connection on right			
	16	90	563 367	DRQD-B-16-90-PPVJ-A-AR-FW
	16	180	563 353	DRQD-B-16-180-PPVJ-A-AR-FW
	20		563 354	DRQD-B-20-180-PPVJ-A-AR-FW
	25		563 355	DRQD-B-25-180-PPVJ-A-AR-FW
	32		563 356	DRQD-B-25-180-PPVJ-A-AR-FW
	YSRJ – Adjustable shock absorbers			
	AL – Connection on left			
	16	180	563 337	DRQD-B-16-180-YSRJ-A-AL-FW
	20		563 338	DRQD-B-20-180-YSRJ-A-AL-FW
	25		563 339	DRQD-B-25-180-YSRJ-A-AL-FW
	32		563 340	DRQD-B-32-180-YSRJ-A-AL-FW
	AR – Connection on right			
	16	180	563 349	DRQD-B-16-180-YSRJ-A-AR-FW
	20	180	563 350	DRQD-B-20-180-YSRJ-A-AR-FW
	25		563 351	DRQD-B-25-180-YSRJ-A-AR-FW
	32		563 352	DRQD-B-32-180-YSRJ-A-AR-FW

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Ordering data – Modular products

M Mandatory data →

Module No.	Function	Product design	Size	Swivel angle	Cushioning	Position sensing	Pneumatic connection	Output shaft
563 345	DRQD	B	16	90	PPVJ	A	AL	ZW
563 346			20	180	YSRJ		AR	FW
563 347			25	360				
563 348			32	1 ... 340				
Ordering example								
563348	DRQD	- B	- 32	- 280	- YSRJ	- A	- AR	- FW

Ordering table		16	20	25	32	Condi- tions	Code	Enter code
Size								
M Module No.		563 345	563 346	563 347	563 348			
Function	Semi-rotary drive with twin pistons						DRQD	DRQD
Product design	Function-optimized						-B	-B
Piston Ø [mm]	16	20	25	32		-...		
Swivel angle (standard)	90°						-90	
Adjusting range +6°/-20° (not preset)	180°						-180	
	360°					[1]	-360	
X-rotation angle	1° ... 70°, with centre section 90°						-...	
Adjusting range ±6°	100° ... 160°, with centre section 180°						-...	
Angle preset ±1°	190° ... 340°, with centre section 360°					[1]	-...	
Cushioning	Adjustable end-position cushioning						-PPVJ	
	Adjustable shock absorbers						-YSRJ	
Position sensing	For proximity sensing						-A	-A
Pneumatic connection	Connection on left						-AL	
	Connection on right						-AR	
Output shaft	Spigot shaft					[2]	-ZW	
	Flanged shaft					[3]	-FW	

[1] **190 ... 360** Not with energy through-feed E422, E444

[2] **ZW** Not with energy through-feed SD32, SD42, E422, E444

[3] **FW** Required for energy through-feed SD32, SD42, E422, E444

Transfer order code

DRQD - **B** - - - **A** - -

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Ordering data – Modular products

FESTO

→ **0** Options

Intermediate position	Energy through-feed	User's manual
Z1	SD32 SD42 E422 E444	B E F S I V
-	- SD42 -	- B -

Ordering table							
Size	16	20	25	32	Condi- tions	Code	Enter code
0 Intermediate position	1 intermediate position (mid-position)				4	-Z1	
Energy through-feed	2x tubing O.D. 3 mm					-SD32	
	2x tubing O.D. 4 mm					-SD42	
	2x tubing O.D. 4 mm, 1x 4-pin cable to 2x 3-pin cable		-	-		-E422	
	-		-	4x tubing O.D. 4 mm, 2x 4-pin cable to 4x 3-pin cable			-E444
Alternative language user docu- mentation (standard is German)	No user manual to be included					-B	
	User manual English					-E	
	User manual French					-F	
	User manual Spanish					-S	
	User manual Italian					-I	
	User manual Swedish					-V	

4 **Z1** Cannot be combined with swivel angle (standard) 360° and X swivel angle

Transfer order code

- - -

Semi-rotary drives DRQD-40 ... 50, twin-pistons



Ordering data – Modular products

M Mandatory data →

Module No.	Function	Size	Swivel angle	Cushioning	Position sensing	Pneumatic connection	Output shaft
197 373	DRQD	40	90	PPVJ	A	AL	ZW
197 374		50	180 360 1 ... 340	YSRJ		AR	FW
Ordering example							
197 373	DRQD	- 40	- 280	- YSRJ	- A	- AR	- FW

Ordering table

Size	40	50	Condi- tions	Code	Enter code
M Module No.	197 373	197 374			
Function	Semi-rotary drive with twin pistons			DRQD	DRQD
Piston Ø [mm]	40	50		-...	
Swivel angle (standard)	90°			-90	
Adjusting range +6°/-20° (not preset)	180°			-180	
	360°		[1]	-360	
X-rotation angle	1° ... 70°, with centre section 90°			-...	
Adjusting range ±6°	100° ... 160°, with centre section 180°			-...	
Angle preset ±1°	190° ... 340°, with centre section 360°		[1]	-...	
Cushioning	Adjustable end-position cushioning			-PPVJ	
	Adjustable shock absorbers			-YSRJ	
Position sensing	For proximity sensing			-A	-A
Pneumatic connection	Connection on left			-AL	
	Connection on right			-AR	
Output shaft	Spigot shaft		[2]	-ZW	
	Flanged shaft		[3]	-FW	

[1] **190 ... 360** Not with energy through-feed E644

[3] **FW** Required for energy through-feed SD48, SD62, SD64, E644

[2] **ZW** Not with energy through-feed SD48, SD62, SD64, E644

Transfer order code

DRQD - - - - **A** - -

Semi-rotary drives DRQD-40 ... 50, twin-pistons

Ordering data – Modular product system



→ **0** Options

Intermediate position	Energy through-feed	User's manual
Z1	SD48 SD62 SD64 E644	B E F S I V
-	- SD64 -	- B -

Ordering table					
Size	40	50	Condi- tions	Code	Enter code
0 Intermediate position	1 intermediate position (mid-position)		4	-Z1	
Energy through-feed	8x tubing O.D. 4 mm			-SD48	
	2x tubing O.D. 6 mm			-SD62	
	4x tubing O.D. 6 mm			-SD64	
	4x tubing O.D. 6 mm, 4x 3-pin cable			-E644	
Alternative language user docu- mentation (standard is German)	No user manual to be included			-B	
	User manual English			-E	
	User manual French			-F	
	User manual Spanish			-S	
	User manual Italian			-I	
	User manual Swedish			-V	

4 **Z1** Cannot be combined with swivel angle (standard) 360° and X swivel angle



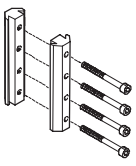

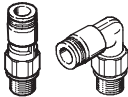
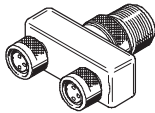
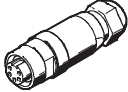
Transfer order code

- - -

Semi-rotary drives DRQD/DRQD-B, twin pistons

Accessories







Ordering data						
	For Ø	Remarks	Design	Part No.	Type	PU ¹⁾
Centring sleeve ZBH			Technical data → Internet: zbh			
	6	For centring the drive on attachments		186 717	ZBH-7	10
	8 ... 32			150 927	ZBH-9	
	40/50			191 409	ZBH-15	
	16/20	For centring attachments on the flanged shaft FW		186 717	ZBH-7	
	25/32			150 927	ZBH-9	
	40/50			189 653	ZBH-12	
Connecting sleeve ZBV			Technical data → Internet: zbv			
	25 ... 32	For centring the semi-rotary drive with a drive		548 806	ZBV-12-9	1
Adapter kit HMSV			Technical data → Internet: hmsv			
	16/20	Mounting via dovetail profile for variant with energy through-feed SD... and E...		177 647	HMSV-1	1
Slot nut NST			Technical data → Internet: nst			
	25 ... 50	Mounting via profile slot nut for variant with energy through-feed SD... and E...		150 914	NST-5-M5	1
Rotary push-in fitting			Technical data → Internet: quick star			
	6 ... 12 Only in combination with hollow bolt HS	With ball bearing, for standard O.D. tubing	Straight	153 526	QSR-M5-4	1
			L-shape	153 529	QSRL-M5-4	
T-connector NEDU			Technical data → Internet: nedu			
	16 ... 32	Included in the scope of delivery if semi-rotary drive DRQD is ordered with energy through-feed E422 and E444. Suitable for connection of two proximity sensors SME/SMT-8 or SME/SMT-10		544 391	NEDU-M8D3-M8T4	1
Cable socket NECU			Technical data → Internet: necu			
	16 ... 32	Included in the scope of delivery if semi-rotary drive DRQD is ordered with energy through-feed E422 and E444.		544 392	NECU-M8G4	1



1) Packaging unit quantity




Semi-rotary drives DRQD/DRQD-B, twin pistons

Accessories

Ordering data – Proximity sensors for C-slot, magneto-resistive						Technical data → Internet: smt
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire, in-line	2.5	525 915	SMT-10F-PS-24V-K2,5L-OE
			Plug M8x1, 3-pin, in-line	0.3	525 916	SMT-10F-PS-24V-K0,3L-M8D
			Plug M8x1, 3-pin, lateral	0.3	526 675	SMT-10F-PS-24V-K0,3Q-M8D
	Insertable in the slot lengthwise	PNP	Plug M8x1, 3-pin, in-line	0.3	173 220	SMT-10-PS-SL-LED-24
			Cable, 3-wire, in-line	2.5	173 218	SMT-10-PS-KL-LED-24

Ordering data – Proximity sensors for C-slot, magnetic reed						Technical data → Internet: sme
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	Contacting	Plug M8x1, 3-pin, in-line	0.3	525 914	SME-10F-DS-24V-K0,3L-M8D
			Cable, 3-wire, in-line	2.5	525 913	SME-10F-DS-24V-K2,5L-OE
			Cable, 2-wire, in-line	2.5	526 672	SME-10F-ZS-24V-K2,5L-OE
	Insertable in the slot lengthwise	Contacting	Plug M8x1, 3-pin, in-line	0.3	173 212	SME-10-SL-LED-24
			Cable, 3-wire, in-line	2.5	173 210	SME-10-KL-LED-24

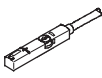


Ordering data – Connecting cables				Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No. Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333 NEBU-M8G3-K-2.5-LE3
			5	541 334 NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338 NEBU-M8W3-K-2.5-LE3
			5	541 341 NEBU-M8W3-K-5-LE3



Ordering data – Proximity sensors for T-slot, magneto-resistive						Technical data → Internet: smt
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	2.5	543 867	SMT-8M-PS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 866	SMT-8M-PS-24V-K-0,3-M8D
			Plug M12x1, 3-pin	0.3	543 869	SMT-8M-PS-24V-K-0,3-M12
		NPN	Cable, 3-wire	2.5	543 870	SMT-8M-NS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 871	SMT-8M-NS-24V-K-0,3-M8D
	Insertable in the slot lengthwise, flush with the cylinder profile	PNP	Cable, 3-wire	2.5	175 436	SMT-8-PS-K-LED-24-B
			Plug M8x1, 3-pin	0.3	175 484	SMT-8-PS-S-LED-24-B
N/C contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543 873	SMT-8M-PO-24V-K7,5-OE

Semi-rotary drives DRQD/DRQD-B, twin pistons

FESTO

Accessories

Ordering data – Proximity sensors for T-slot, magnetic reed					Technical data → Internet: sme	
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	Contacting	Cable, 3-wire	2.5	543 862	SME-8M-DS-24V-K-2,5-OE
				5.0	543 863	SME-8M-DS-24V-K-5,0-OE
			Cable, 3-wire	2.5	543 872	SME-8M-ZS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 861	SME-8M-DS-24V-K-0,3-M8D
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	2.5	150 855	SME-8-K-LED-24
			Plug M8x1, 3-pin	0.3	150 857	SME-8-S-LED-24
N/C contact						
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	160 251	SME-8-0-K-LED-24

Ordering data – Connecting cables				Technical data → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Straight socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 363	NEBU-M12G5-K-2.5-LE3
			5	541 364	NEBU-M12G5-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3
	Angled socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 367	NEBU-M12W5-K-2.5-LE3
			5	541 370	NEBU-M12W5-K-5-LE3

Ordering data – Slot cover for T-slot			
	Assembly	Length [m]	Part No. Type
	Insertable from above	2x 0.5	151 680 ABP-5-S

What must be observed when using Festo components?

Specified limit values for technical data and any specific instructions must be adhered to by the user in order to ensure recommended operating conditions.

When pneumatic components are used, the user shall ensure that they are operated using correctly prepared compressed air without aggressive media.

When Festo components are used in safety-oriented applications, the user shall ensure that all applicable

national and local safety laws and regulations, for example the machine directive, together with the relevant references to standards are observed. Unauthorised conversions or modifications to products and systems from Festo involve a safety risk and are thus not permissible.

Festo does not accept any liability for resulting damages.

You should contact Festo's advisors if one of the following apply to your application:

- The ambient conditions and conditions of use or the operating medium differ from the specified technical data.
- The product is to perform a safety function.
- A risk or safety analysis is required.
- You are unsure about the product's suitability for use in the planned application.
- You are unsure about the product's suitability for use in safety-oriented applications.

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